

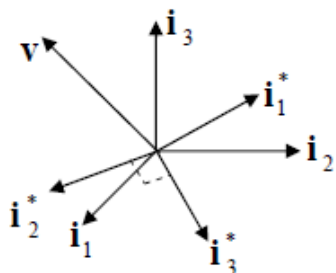
1. Two Cartesian bases,  $(\mathbf{i}_i)$ , and  $(\mathbf{i}_i^*)$  are given as below, with  $\mathbf{i}_1^* = (2\mathbf{i}_1 + 2\mathbf{i}_2 + \mathbf{i}_3)/3$  and  $\mathbf{i}_2^* = (\mathbf{i}_1 - \mathbf{i}_2)/\sqrt{2}$ .

(a) Express  $\mathbf{i}_3^*$  in terms of  $(\mathbf{i}_i)$ .

(b) Express  $(\mathbf{i}_i)$  in terms of the  $(\mathbf{i}_i^*)$ .

(c) Let  $\mathbf{v} = 6\mathbf{i}_1 - 6\mathbf{i}_2 + 12\mathbf{i}_3$ . Find the  $v_i^*$ , the components of the vector  $\mathbf{v}$  in the  $(\mathbf{i}_i^*)$  basis.

(d) verify your answer of part (c).



a)

$$\mathbf{i}_3^* = \mathbf{i}_1^* \times \mathbf{i}_2^* = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 2/3 & 2/3 & 1/3 \\ 1/\sqrt{2} & -1/\sqrt{2} & 0 \end{vmatrix} = \left(\frac{1}{3\sqrt{2}}\right)\mathbf{i} + \left(\frac{1}{3\sqrt{2}}\right)\mathbf{j} + \left(\frac{-2}{3\sqrt{2}} - \frac{2}{3\sqrt{2}}\right)\mathbf{k}$$

$$= \left(\frac{1}{3\sqrt{2}}\right)\mathbf{i} + \left(\frac{1}{3\sqrt{2}}\right)\mathbf{j} + \left(\frac{-4}{3\sqrt{2}}\right)\mathbf{k} = \left(\frac{1}{3\sqrt{2}}\right)(\mathbf{i} + \mathbf{j} - 4\mathbf{k})$$

b)

$$\begin{bmatrix} \mathbf{i}^* \\ \mathbf{j}^* \\ \mathbf{k}^* \end{bmatrix} = \begin{bmatrix} 2/3 & 2/3 & 1/3 \\ 1/\sqrt{2} & -1/\sqrt{2} & 0 \\ 1/3\sqrt{2} & 1/3\sqrt{2} & -4/3\sqrt{2} \end{bmatrix} \begin{bmatrix} \mathbf{i} \\ \mathbf{j} \\ \mathbf{k} \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{i} \\ \mathbf{j} \\ \mathbf{k} \end{bmatrix} = \begin{bmatrix} 2/3 & 1/\sqrt{2} & 1/3\sqrt{2} \\ 2/3 & -1/\sqrt{2} & 1/3\sqrt{2} \\ 1/3 & 0 & -4/\sqrt{6} \end{bmatrix} \begin{bmatrix} \mathbf{i}^* \\ \mathbf{j}^* \\ \mathbf{k}^* \end{bmatrix}$$

(c) Let  $\mathbf{v} = 6\mathbf{i}_1 - 6\mathbf{i}_2 + 12\mathbf{i}_3$ . Find the  $v_i^*$ , the components of the vector  $\mathbf{v}$  in the  $(\mathbf{i}_i^*)$  basis.

$$\begin{bmatrix} V_{\mathbf{i}^*} \\ V_{\mathbf{j}^*} \\ V_{\mathbf{k}^*} \end{bmatrix} = \begin{bmatrix} 2/3 & 2/3 & 1/3 \\ 1/\sqrt{2} & -1/\sqrt{2} & 0 \\ 1/3\sqrt{2} & 1/3\sqrt{2} & -4/3\sqrt{2} \end{bmatrix} \begin{bmatrix} 6 \\ -6 \\ 12 \end{bmatrix}$$

$$V_{\mathbf{i}^*} = 4 - 4 + 4 = 4$$

$$V_{\mathbf{j}^*} = 6/\sqrt{2} + 6/\sqrt{2} = 12/\sqrt{2}$$

$$V_{\mathbf{k}^*} = 6/3\sqrt{2} - 6/3\sqrt{2} - 16\sqrt{2} = -16/\sqrt{2}$$

d) check norm

$$\text{norm}[6 \ -6 \ 12] = 14.6969$$

$$\text{norm}[4 \ 12/\sqrt{2} \ -16/\sqrt{2}] = 14.6969$$

$$\begin{bmatrix} \mathbf{i}^* \\ \mathbf{j}^* \\ \mathbf{k}^* \end{bmatrix} = \begin{bmatrix} 2/3 & 2/3 & 1/3 \\ 1/\sqrt{2} & -1/\sqrt{2} & 0 \\ 1/\sqrt{6} & 1/\sqrt{6} & -4/\sqrt{6} \end{bmatrix} \begin{bmatrix} \mathbf{i} \\ \mathbf{j} \\ \mathbf{k} \end{bmatrix}$$

2. Recall the following definitions for *divergence*, *curl*, and *gradient* of a vector field

$$\mathbf{v} = v_i(x_j) \mathbf{i}_i:$$

$$\nabla \cdot \mathbf{v} = v_{i,i} = \text{trace} \nabla \mathbf{v}$$

$$\nabla \times \mathbf{v} = \varepsilon_{ijk} v_{k,j} \mathbf{i}_i$$

$$\nabla \mathbf{v} = v_{i,j} \mathbf{i}_i \otimes \mathbf{i}_j \text{ [note the order of the indices; it's how we define the gradient tensor]}$$

Let the position vector be  $\mathbf{r} = x_i \mathbf{i}_i$ . Compute

(a)  $\nabla \mathbf{r}$ ,

(b)  $\nabla \cdot \mathbf{r}$

(c)  $\nabla \times \mathbf{r}$

$$\text{a) } \nabla \mathbf{r} = x_{i,j} \mathbf{i}_i \otimes \mathbf{i}_j = \begin{bmatrix} x_{i,i} & x_{i,j} & x_{i,k} \\ x_{j,i} & x_{j,j} & x_{j,k} \\ x_{k,i} & x_{k,j} & x_{k,k} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{b) } \nabla \cdot \mathbf{r} = \frac{\partial}{\partial x_i} \mathbf{i}_i \cdot x_j \mathbf{i}_j = \frac{\partial}{\partial x_i} x_j \delta_{ij} = x_{i,i} = 3$$

$$\text{c) } \nabla \times \mathbf{r} = \frac{\partial}{\partial x_i} \mathbf{i}_i \times (x_j \mathbf{i}_j) = \varepsilon_{ijk} \frac{\partial}{\partial x_i} x_j \mathbf{i}_k = \varepsilon_{ijk} x_{j,i} \mathbf{i}_k = 0$$

3. For an arbitrary *scalar* function  $\phi = \phi(x_i)$ , and an arbitrary *vector* function  $\mathbf{v} = \mathbf{v}(x_i)$ , prove that

(a)  $\nabla \times \nabla \phi = 0$ ;

(b)  $\nabla \cdot (\nabla \times \mathbf{v}) = 0$ .

The curl of the gradient of a scalar is zero.

$$\text{a) } \nabla_x \nabla \phi = \nabla_x \frac{\partial \phi}{\partial x_j} \mathbf{i}_j = \frac{\partial}{\partial x_i} \left( \frac{\partial \phi}{\partial x_j} \right) \epsilon_{ijk} \mathbf{i}_k$$

$$\nabla_x \nabla \phi = \left( \frac{\partial^2 \phi}{\partial x_2 \partial x_3} - \frac{\partial^2 \phi}{\partial x_3 \partial x_2} \right) \mathbf{i}_1 + \left( \frac{\partial^2 \phi}{\partial x_3 \partial x_1} - \frac{\partial^2 \phi}{\partial x_1 \partial x_3} \right) \mathbf{i}_2 + \left( \frac{\partial^2 \phi}{\partial x_1 \partial x_2} - \frac{\partial^2 \phi}{\partial x_2 \partial x_1} \right) \mathbf{i}_3$$

If the scalar field  $\phi$  is twice continuously differentiable, then its second derivatives are independent of the order in which the derivatives are applied.

$$\frac{\partial^2 \phi}{\partial x_j \partial x_k} - \frac{\partial^2 \phi}{\partial x_k \partial x_j} = 0$$

$$\nabla_x \nabla \phi = 0 \mathbf{i}_k = 0$$

b)

$$\nabla \cdot \nabla_x \mathbf{v} = \nabla \cdot \left( \frac{\partial}{\partial x_i} v_j \epsilon_{ijk} \mathbf{i}_k \right) = \frac{\partial}{\partial x_m} \cdot \left( \frac{\partial}{\partial x_i} v_j \epsilon_{ijk} \right) \delta_{km}$$

$$\nabla \cdot \nabla_x \mathbf{v} = \nabla \cdot \left[ \left( \frac{\partial v_3}{\partial x_2} - \frac{\partial v_2}{\partial x_3} \right) \mathbf{i}_1 + \left( \frac{\partial v_1}{\partial x_3} - \frac{\partial v_3}{\partial x_1} \right) \mathbf{i}_2 + \left( \frac{\partial v_2}{\partial x_1} - \frac{\partial v_1}{\partial x_2} \right) \mathbf{i}_3 \right]$$

$$\nabla \cdot \nabla_x \mathbf{V} = \left[ \frac{\partial}{\partial x_1} \mathbf{i}_1 + \frac{\partial}{\partial x_2} \mathbf{i}_2 + \frac{\partial}{\partial x_3} \mathbf{i}_3 \right] \cdot \left[ \left( \frac{\partial V_3}{\partial x_2} - \frac{\partial V_2}{\partial x_3} \right) \mathbf{i}_1 + \left( \frac{\partial V_1}{\partial x_3} - \frac{\partial V_3}{\partial x_1} \right) \mathbf{i}_2 + \left( \frac{\partial V_2}{\partial x_1} - \frac{\partial V_1}{\partial x_2} \right) \mathbf{i}_3 \right]$$

$$\nabla \cdot \nabla_x \mathbf{V} = \left[ \frac{\partial}{\partial x_1} \left( \frac{\partial V_3}{\partial x_2} - \frac{\partial V_2}{\partial x_3} \right) + \frac{\partial}{\partial x_2} \left( \frac{\partial V_1}{\partial x_3} - \frac{\partial V_3}{\partial x_1} \right) + \frac{\partial}{\partial x_3} \left( \frac{\partial V_2}{\partial x_1} - \frac{\partial V_1}{\partial x_2} \right) \right]$$

$$\nabla \cdot \nabla_x \mathbf{V} = \left[ \frac{\partial^2 V_3}{\partial x_1 \partial x_2} - \frac{\partial^2 V_2}{\partial x_1 \partial x_3} + \frac{\partial^2 V_1}{\partial x_2 \partial x_3} - \frac{\partial^2 V_3}{\partial x_1 \partial x_2} + \frac{\partial^2 V_2}{\partial x_1 \partial x_3} - \frac{\partial^2 V_1}{\partial x_2 \partial x_3} \right]$$

$$\nabla \cdot \nabla_x \mathbf{V} = 0$$

4. Show that the *triple scalar product* is skew-symmetric with respect to changing the order in which the vector appear in the product. For example, show that

$$(\mathbf{u} \times \mathbf{v}) \cdot \mathbf{w} = -(\mathbf{v} \times \mathbf{u}) \cdot \mathbf{w}$$

To generalize this notion, any cyclic permutation (e.g.,  $\mathbf{u}, \mathbf{v}, \mathbf{w} \rightarrow \mathbf{w}, \mathbf{u}, \mathbf{v}$ ) of the order of the vectors leaves the sign of the product unchanged, while any acyclic permutation (e.g.,  $\mathbf{u}, \mathbf{v}, \mathbf{w} \rightarrow \mathbf{u}, \mathbf{w}, \mathbf{v}$ ) of the order of the vectors changes the sign. How does this observation relate to the swapping rows of a matrix in the computation of the determinant of that matrix?

$$(\mathbf{u} \times \mathbf{v}) \cdot \mathbf{w} = -(\mathbf{v} \times \mathbf{u}) \cdot \mathbf{w}$$

$$(\varepsilon_{ijk} u_i v_j i_k) \cdot w_m i_m = -(\varepsilon_{jik} v_j u_i i_k) \cdot w_m i_m$$

$$(\varepsilon_{ijk} u_i v_j i_k) \cdot w_m i_m = -(\varepsilon_{jik} u_i v_j i_k) \cdot w_m i_m$$

$$\varepsilon_{ijk} u_i v_j w_m \delta_{km} = -\varepsilon_{jik} u_i v_j w_m \delta_{km}$$

$$\varepsilon_{ijk} u_i v_j w_k = -\varepsilon_{jik} u_i v_j w_k$$

$$\varepsilon_{ijk} = -\varepsilon_{jik}$$

5. Let  $\phi(\mathbf{r}) = x_2x_3 + x_1x_3 + x_1x_2$  be a *scalar* field.

(a) Compute the gradient  $\nabla\phi$  of the field;

(b) Verify  $\nabla \times \nabla\phi = 0$ .

a)

$$\phi(\mathbf{r}) = x_2x_3 + x_1x_3 + x_1x_2$$

$$\begin{aligned}\nabla\phi &= \frac{\partial}{\partial x_1}(x_2x_3 + x_1x_3 + x_1x_2)\mathbf{i}_1 \\ &\quad + \frac{\partial}{\partial x_2}(x_2x_3 + x_1x_3 + x_1x_2)\mathbf{i}_2 \\ &\quad + \frac{\partial}{\partial x_3}(x_2x_3 + x_1x_3 + x_1x_2)\mathbf{i}_3\end{aligned}$$

$$\nabla\phi = (x_3 + x_2)\mathbf{i}_1 + (x_3 + x_1)\mathbf{i}_2 + (x_2 + x_1)\mathbf{i}_3$$

b)  $\nabla_x \nabla\phi = \nabla_x \{(x_3 + x_2)\mathbf{i}_1 + (x_3 + x_1)\mathbf{i}_2 + (x_2 + x_1)\mathbf{i}_3\}$

$$\nabla_x \nabla\phi = \begin{vmatrix} \mathbf{i}_1 & \mathbf{i}_2 & \mathbf{i}_3 \\ \frac{\partial}{\partial x_1} & \frac{\partial}{\partial x_2} & \frac{\partial}{\partial x_3} \\ (x_3 + x_2) & (x_3 + x_1) & (x_2 + x_1) \end{vmatrix}$$

$$\nabla_x \nabla\phi$$

$$\begin{aligned}&= \left( \frac{\partial}{\partial x_2}(x_2 + x_1) - \frac{\partial}{\partial x_3}(x_3 + x_1) \right) \mathbf{i}_1 \\ &\quad + \left( \frac{\partial}{\partial x_3}(x_3 + x_2) - \frac{\partial}{\partial x_1}(x_2 + x_1) \right) \mathbf{i}_2 \\ &\quad + \left( \frac{\partial}{\partial x_1}(x_3 + x_1) + \frac{\partial}{\partial x_2}(x_3 + x_2) \right) \mathbf{i}_3\end{aligned}$$

$$\nabla_x \nabla\phi = (1-1)\mathbf{i}_1 + (1-1)\mathbf{i}_2 + (1-1)\mathbf{i}_3 = 0$$

6. Let  $\mathbf{v}(\mathbf{r}) = x_2x_3\mathbf{i}_1 + x_1x_3\mathbf{i}_2 + x_1x_2\mathbf{i}_3$  be a *vector field*. Compute

(a) the gradient  $\nabla\mathbf{v}$  of the field;

(b) the divergence  $\nabla \cdot \mathbf{v}$  of the field.

a)

$$\mathbf{v}(\mathbf{r}) = x_2x_3\mathbf{i}_1 + x_1x_3\mathbf{i}_2 + x_1x_2\mathbf{i}_3$$

$$\nabla\mathbf{v} = \begin{bmatrix} V_{1,1} & V_{1,2} & V_{1,3} \\ V_{2,1} & V_{2,2} & V_{2,3} \\ V_{3,1} & V_{3,2} & V_{3,3} \end{bmatrix} = \begin{bmatrix} 0 & x_3 & x_2 \\ x_3 & 0 & x_1 \\ x_2 & x_1 & 0 \end{bmatrix}$$

b) 
$$\nabla \cdot \mathbf{v}(\mathbf{r}) = \left( \frac{\partial}{\partial x_1} \mathbf{i}_1 + \frac{\partial}{\partial x_2} \mathbf{i}_2 + \frac{\partial}{\partial x_3} \mathbf{i}_3 \right) \cdot (x_2x_3\mathbf{i}_1 + x_1x_3\mathbf{i}_2 + x_1x_2\mathbf{i}_3)$$

$$\nabla \cdot \mathbf{v}(\mathbf{r}) = \left( \frac{\partial}{\partial x_1} x_2x_3 + \frac{\partial}{\partial x_2} x_1x_3 + \frac{\partial}{\partial x_3} x_1x_2 \right) = 0$$

7. Let  $\mathbf{u}(\mathbf{r})$ ,  $\mathbf{v}(\mathbf{r})$ ,  $\mathbf{w}(\mathbf{r})$  be vector fields and let  $\mathbf{T}(\mathbf{r})$  be a tensor (2<sup>nd</sup>-order) field. Compute the component forms of the following derivatives

- (a)  $\nabla(\mathbf{u} \cdot \mathbf{v})$ ,      (b)  $\nabla \cdot (\mathbf{u} \times \mathbf{v})$ ,      (c)  $\nabla(\mathbf{u} \times \mathbf{v})$ ,  
 (d)  $\nabla \cdot (\mathbf{T}\mathbf{v})$ ,      (e)  $\nabla(\mathbf{u} \cdot \mathbf{T}\mathbf{v})$ ,      (f)  $\nabla(\mathbf{T}\mathbf{v})$ ,  
 (g)  $\nabla \cdot (\mathbf{u} \otimes \mathbf{v})$ ,      (h)  $\nabla \cdot ([\mathbf{u} \otimes \mathbf{v}]\mathbf{w})$ ,      (i)  $\nabla[(\mathbf{u} \times \mathbf{v}) \cdot \mathbf{w}]$ .

$$(\mathbf{u} \times \mathbf{v}) = (u_i v_j \varepsilon_{ijk} \mathbf{i}_k) = \begin{vmatrix} \mathbf{i}_1 & \mathbf{i}_2 & \mathbf{i}_3 \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} = (u_2 v_3 - u_3 v_2) \mathbf{i}_1 + (u_3 v_1 - u_1 v_3) \mathbf{i}_2 + (u_1 v_2 - u_2 v_1) \mathbf{i}_3$$

a)  $\nabla(\mathbf{u} \cdot \mathbf{v}) = \nabla(u_i v_j \delta_{ij}) = \nabla(u_i v_i) = \frac{\partial}{\partial x_k} (u_i v_i) \mathbf{i}_k = (u_i v_i)_{,k} \mathbf{i}_k = (u_{i,k} v_i + u_i v_{i,k}) \mathbf{i}_k$

b)

$$\begin{aligned} \nabla \cdot (\mathbf{u} \times \mathbf{v}) &= \nabla \cdot (u_i v_j \varepsilon_{ijk} \mathbf{i}_k) = \mathbf{i}_m \frac{\partial}{\partial x_m} \cdot (u_i v_j \varepsilon_{ijk} \mathbf{i}_k) = \frac{\partial}{\partial x_k} (u_i v_j \varepsilon_{ijk}) = \varepsilon_{ijk} (u_i v_j)_{,k} \\ &= \varepsilon_{ijk} (u_{i,k} v_j + u_i v_{j,k}) \end{aligned}$$

c)  $\nabla(\mathbf{u} \times \mathbf{v}) = \begin{vmatrix} \frac{\partial}{\partial x_1} (u_2 v_3 - u_3 v_2) & \frac{\partial}{\partial x_2} (u_2 v_3 - u_3 v_2) & \frac{\partial}{\partial x_3} (u_2 v_3 - u_3 v_2) \\ \frac{\partial}{\partial x_1} (u_3 v_1 - u_1 v_3) & \frac{\partial}{\partial x_2} (u_3 v_1 - u_1 v_3) & \frac{\partial}{\partial x_3} (u_3 v_1 - u_1 v_3) \\ \frac{\partial}{\partial x_1} (u_1 v_2 - u_2 v_1) & \frac{\partial}{\partial x_2} (u_1 v_2 - u_2 v_1) & \frac{\partial}{\partial x_3} (u_1 v_2 - u_2 v_1) \end{vmatrix}$



d)

$$\begin{aligned}\nabla \cdot (\mathbf{T} \mathbf{v}) &= \nabla \cdot (\mathbf{T}_{ij} \mathbf{i}_i \otimes \mathbf{i}_j) \mathbf{v}_j \mathbf{i}_j \\ &= \nabla \cdot (\mathbf{T}_{ij} \mathbf{v}_j) (\mathbf{i}_i (\mathbf{i}_j \cdot \mathbf{i}_j)) \\ &= \nabla \cdot (\mathbf{T}_{ij} \mathbf{v}_j) (\mathbf{i}_i (\mathbf{i}_j \cdot \mathbf{i}_j)) \\ &= \nabla \cdot \mathbf{T}_{ij} \mathbf{v}_j \mathbf{i}_i \\ &= \frac{\partial}{\partial x_k} \mathbf{T}_{ij} \mathbf{v}_j \delta_{ik} \\ &= \frac{\partial}{\partial x_i} \mathbf{T}_{ij} \mathbf{v}_j \\ &= (\mathbf{T}_{ij} \mathbf{v}_j)_{,i} = (\mathbf{T}_{ij,i} \mathbf{v}_j + \mathbf{T}_{ij} \mathbf{v}_{j,i})\end{aligned}$$

e)  $\nabla(\mathbf{u} \cdot \mathbf{T} \mathbf{v})$

$$\nabla(\mathbf{u} \cdot \mathbf{T} \mathbf{v}) = \nabla(\mathbf{u} \cdot \mathbf{T}_{ij} \mathbf{v}_j \mathbf{i}_i)$$

$$\nabla(\mathbf{u} \cdot \mathbf{T} \mathbf{v}) = \nabla(u_i \mathbf{T}_{ij} \mathbf{v}_j)$$

$$\nabla(\mathbf{u} \cdot \mathbf{T} \mathbf{v}) = \frac{\partial}{\partial x_k} (u_i \mathbf{T}_{ij} \mathbf{v}_j) \mathbf{i}_k$$

$$\nabla(\mathbf{u} \cdot \mathbf{T} \mathbf{v}) = (u_i \mathbf{T}_{ij} \mathbf{v}_j)_{,k} \mathbf{i}_k = (u_{i,k} \mathbf{T}_{ij} \mathbf{v}_j + u_i \mathbf{T}_{ij,k} \mathbf{v}_j + u_i \mathbf{T}_{ij} \mathbf{v}_{j,k}) \mathbf{i}_k$$

f)

$$\nabla(\mathbf{T} \mathbf{v}) = \nabla(T_{ij} v_j \mathbf{i}_i) = \nabla(T_{1j} v_j \mathbf{i}_1 + T_{2j} v_j \mathbf{i}_2 + T_{3j} v_j \mathbf{i}_3)$$

$$= \begin{vmatrix} \frac{\partial}{\partial x_1} T_{1j} v_j & \frac{\partial}{\partial x_2} T_{1j} v_j & \frac{\partial}{\partial x_3} T_{1j} v_j \\ \frac{\partial}{\partial x_1} T_{2j} v_j & \frac{\partial}{\partial x_2} T_{2j} v_j & \frac{\partial}{\partial x_3} T_{2j} v_j \\ \frac{\partial}{\partial x_1} T_{3j} v_j & \frac{\partial}{\partial x_2} T_{3j} v_j & \frac{\partial}{\partial x_3} T_{3j} v_j \end{vmatrix} = \frac{\partial}{\partial x_k} T_{ij} v_j \mathbf{i}_i \otimes \mathbf{i}_k = (T_{ij,k} v_j + T_{ij} v_{j,k}) \mathbf{i}_i \otimes \mathbf{i}_k$$

$$\text{g) } \nabla \cdot (\mathbf{u} \otimes \mathbf{v}) = \frac{\partial}{\partial x_k} \mathbf{i}_k \cdot [u_i v_j \mathbf{i}_i \otimes \mathbf{i}_j] = \frac{\partial}{\partial x_j} [u_i v_j] \mathbf{i}_i = [u_{i,j} v_j + u_i v_{j,j}] \mathbf{i}_i$$

h)

$$\begin{aligned}\nabla \cdot ([\mathbf{u} \otimes \mathbf{v}] \mathbf{w}) &= \nabla \cdot (\mathbf{u}(\mathbf{v} \cdot \mathbf{w})) \\ &= \nabla \cdot \mathbf{u}(\mathbf{v}_i \mathbf{w}_i) \\ &= \frac{\partial}{\partial x_k} [\mathbf{u}_k (\mathbf{v}_i \mathbf{w}_i)] \\ &= [\mathbf{u}_k (\mathbf{v}_i \mathbf{w}_i)]_{,k} = \mathbf{u}_{k,k} \mathbf{v}_i \mathbf{w}_i + \mathbf{u}_k \mathbf{v}_{i,k} \mathbf{w}_i + \mathbf{u}_k \mathbf{v}_i \mathbf{w}_{i,k}\end{aligned}$$

i)

$$\begin{aligned}\nabla((\mathbf{u} \times \mathbf{v}) \cdot \mathbf{w}) &= \nabla(\mathbf{u}_i \mathbf{v}_j \varepsilon_{ijk} \mathbf{i}_k \cdot \mathbf{w}) = \nabla(\mathbf{u}_i \mathbf{v}_j \mathbf{w}_k \varepsilon_{ijk}) \\ &= \frac{\partial}{\partial x_m} (\mathbf{u}_i \mathbf{v}_j \mathbf{w}_k \varepsilon_{ijk}) \mathbf{i}_m \\ &= \varepsilon_{ijk} (\mathbf{u}_{i,m} \mathbf{v}_j \mathbf{w}_k + \mathbf{u}_i \mathbf{v}_{j,m} \mathbf{w}_k + \mathbf{u}_i \mathbf{v}_j \mathbf{w}_{k,m}) \mathbf{i}_m\end{aligned}$$