# PLATE POINT MOBILITY

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## Variables

| f               | Excitation frequency                                                                                                                                           |
|-----------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------|
| f <sub>mn</sub> | Natural frequency for mode <i>m</i> , <i>n</i>                                                                                                                 |
| $H_{v,ij}(f)$   | The steady state velocity at coordinate <i>i</i> due to a harmonic force excitation only at coordinate <i>j</i> . This is also known as the mobility function. |
| ξmn             | Damping ratio for mode <i>m</i> , <i>n</i>                                                                                                                     |
| $\phi_{imn}$    | Mass-normalized eigenvector for physical coordinate $i$ and mode number $m, n$                                                                                 |
| ω               | Excitation frequency (rad/sec)                                                                                                                                 |
| ω <sub>mn</sub> | Natural frequency (rad/sec) for mode <i>m</i> , <i>n</i>                                                                                                       |

### **Introduction**

Consider a flat plate excited by a harmonic point force.

The steady-state velocity at coordinate i due to a harmonic force excitation only at coordinate j is

$$H_{v,ij}(f) = j\omega \sum_{m n=1}^{M} \sum_{n=1}^{N} \left\{ \frac{\phi_{imn} \phi_{jmn}}{\omega_{mn}^{2}} \frac{1}{\left[ \left( 1 - \rho_{mn}^{2} \right) + j \left( 2\xi_{mn} \rho_{mn} \right) \right]} \right\}$$
(1)

where

$$\rho_{mn} = f / f_{mn}$$
  
 $j = \sqrt{-1}$ 

Note that j is used both as an index and as an imaginary number in equation (1).

Equation (1) is derived from Reference 1.

Now consider a plate simply-supported on all sides. The steady-state velocity at coordinate i due to a harmonic force excitation only at coordinate j is

$$H_{v,ij}(f) = j\omega\left(\frac{4}{\rho a b h}\right) \sum_{m}^{M} \sum_{n=1}^{N} \left\{ \frac{1}{\omega_{mn}^{2}} \frac{\left[\sin\left(\frac{m\pi x}{a}\right)\sin\left(\frac{n\pi y}{b}\right)\right] \left[\sin\left(\frac{m\pi x_{0}}{a}\right)\sin\left(\frac{n\pi y_{0}}{b}\right)\right]}{\left[\left(1-\rho_{mn}^{2}\right)+j\left(2\xi_{mn}\rho_{mn}\right)\right]} \right\}$$
(2)

where

(x,y) is the coordinate for the input index *i* 

 $(x_0,y_0)$  is the coordinate for the input index *j* 

Equation (2) is derived from References 1, 2 and 3.

#### Example

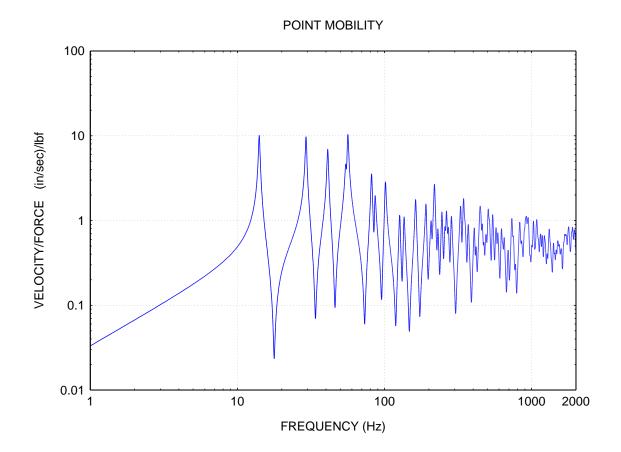


Figure 1.

The point mobility function is shown for an aluminum plate with dimensions (48" x 36" x 0.125").

The input and response are each located at the quarter point along both the length and the width.

The loss factor is 0.02 for all modes.

The theoretical mobility for a 0.125" thick aluminum plate with infinite length and width is 0.55 (in/sec)/lbf, based on Reference 4.

The finite, simply-supported plate in this example has a compliance which roughly converges to this value at frequencies beyond those shown in Figure 1. Note that exact convergence is not expected.

### **References**

- 1. T. Irvine, Calculating Transfer Functions from Normal Modes, Revision B, Vibrationdata, 2010.
- 2. Dr. S. Hambric, Structural-Acoustic Tutorial Part 1- Fundamentals, ASME IMECE, Orlando, Florida, 2009.
- 3. T. Irvine, Natural Frequencies of Rectangular Plate Bending Modes, Revision B, Vibrationdata, 2011.
- 4. T. Irvine, Radiation & Driving Point Impedance of a Thin, Isotropic Plate, Vibrationdata, 2008.