

STEADY-STATE VIBRATION RESPONSE OF A FIXED-FIXED BEAM SUBJECTED TO AN APPLIED FORCE WITH SPATIAL VARIATION

Revision C

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The fixed-fixed beam in Figure 1 is subjected to an applied force with spatial variation.

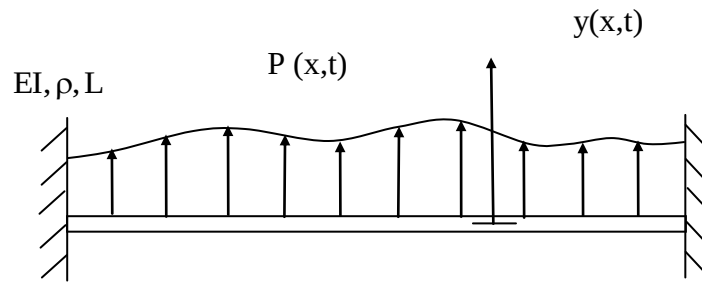


Figure 1.

The following equations are taken from References 1 and 2.

The governing differential equation is

$$EI \frac{\partial^4 y}{\partial x^4} + \rho \frac{\partial^2 y}{\partial t^2} = P(x, t) \quad (1)$$

where

- E is the modulus of elasticity
- I is the area moment of inertia
- L is the length
- ρ is the mass density (mass/length)
- P is the applied force per length

Assume that the pressure field can be represented as

$$P(x, t) = \hat{P}(x)f(t) \quad (2)$$

where $\hat{P}(x)$ is dimensionless

Assume that the displacement field can be represented as

$$y(x, t) = Y(x)T(t) \quad (3)$$

$$EI \frac{\partial^4}{\partial x^4} Y(x)T(t) + \rho \frac{\partial^2}{\partial t^2} Y(x)T(t) = \hat{P}(x)f(t) \quad (4)$$

$$EI \frac{d^4}{dx^4} Y(x)T(t) + \rho Y(x)\ddot{T}(t) = \hat{P}(x)f(t) \quad (5)$$

The homogeneous equation is

$$EI \frac{d^4}{dx^4} Y(x)T(t) + \rho Y(x)\ddot{T}(t) = 0 \quad (6)$$

$$\rho Y(x)\ddot{T}(t) = -EI \frac{d^4}{dx^4} Y(x)T(t) \quad (7)$$

$$\frac{\ddot{T}(t)}{T(t)} = -\frac{EI}{\rho Y(x)} \frac{d^4}{dx^4} Y(x) = -c^2 \quad (8)$$

Thus

$$\frac{d^2}{dt^2} T(t) + c^2 T(t) = 0 \quad (9)$$

$$\left\{ \frac{-EI}{\rho} \right\} \frac{\left\{ \frac{d^4}{dx^4} Y(x) \right\}}{Y(x)} = -c^2 \quad (10)$$

$$\frac{d^4}{dx^4} Y(x) - c^2 \left\{ \frac{\rho}{EI} \right\} Y(x) = 0 \quad (11)$$

A solution for equation (11) is

$$Y(x) = a_1 \sinh(\beta x) + a_2 \cosh(\beta x) + a_3 \sin(\beta x) + a_4 \cos(\beta x) \quad (12)$$

Intermediate steps are given in Reference 1.

The eigenvalues are

N	$\beta_n L$
1	4.73004
2	7.85321
3	10.9956
4	14.13717
5	17.27876

For $n > 5$

$$\beta_n L \approx \pi \left[\frac{1}{2} + n \right] \quad (13)$$

The mass-normalized mode shapes are

$$Y_n(x) = \frac{1}{\sqrt{\rho L}} \{ [\cosh(\beta_n x) - \cos(\beta_n x)] - \sigma_n [\sinh(\beta_n x) - \sin(\beta_n x)] \} \quad (14)$$

where

$$\sigma_n = \left[\frac{\sinh(\beta L) + \sin(\beta L)}{\cosh(\beta L) - \cos(\beta L)} \right]$$

The derivatives are

$$Y_n'(x) = \frac{\beta_n}{\sqrt{\rho L}} \{ [\sinh(\beta_n x) + \sin(\beta_n x)] - \sigma_n [\cosh(\beta_n x) - \cos(\beta_n x)] \} \quad (15)$$

$$Y_n''(x) = \frac{\beta_n^2}{\sqrt{\rho L}} \{ [\cosh(\beta_n x) + \cos(\beta_n x)] - \sigma_n [\sinh(\beta_n x) + \sin(\beta_n x)] \} \quad (16)$$

Recall

$$EI \frac{\partial^4}{\partial x^4} y(x, t) + \rho \frac{\partial^2}{\partial t^2} y(x, t) = \hat{P}(x) f(t) \quad (17)$$

Let

$$y(x, t) = \sum_{n=1}^m Y_n(x) T_n(t) \quad (18)$$

$$EI \frac{\partial^4}{\partial x^4} \left[\sum_{n=1}^m Y_n(x) T_n(t) \right] + \rho \frac{\partial^2}{\partial t^2} \left[\sum_{n=1}^m Y_n(x) T_n(t) \right] = \hat{P}(x) f(t) \quad (19)$$

$$EI \left[\sum_{n=1}^m T_n(t) \frac{\partial^4}{\partial x^4} Y_n(x) \right] + \rho \left[\sum_{n=1}^m Y_n(x) \frac{\partial^2}{\partial t^2} T_n(t) \right] = \hat{P}(x)f(t) \quad (20)$$

$$EI \left[\sum_{n=1}^m T_n(t) \frac{d^4}{dx^4} Y_n(x) \right] + \rho \left[\sum_{n=1}^m Y_n(x) \frac{d^2}{dt^2} T_n(t) \right] = \hat{P}(x)f(t) \quad (21)$$

Note that

$$\frac{d^4}{dx^4} Y_n(x) = \beta_n^4 Y_n(x) \quad (22)$$

By substitution,

$$EI \left[\sum_{n=1}^m \beta_n^4 T_n(t) Y_n(x) \right] + \rho \left[\sum_{n=1}^m Y_n(x) \frac{d^2}{dt^2} T_n(t) \right] = \hat{P}(x)f(t) \quad (23)$$

$$EI \beta_n^4 \left[\sum_{n=1}^m T_n(t) Y_n(x) \right] + \rho \left[\sum_{n=1}^m Y_n(x) \frac{d^2}{dt^2} T_n(t) \right] = -\hat{P}(x)f(t) \quad (24)$$

Multiply each term by $Y_p(x)$.

$$EI \beta_n^4 \left[\sum_{n=1}^m T_n(t) Y_n(x) Y_p(x) \right] + \rho \left[\sum_{n=1}^m Y_n(x) Y_p(x) \frac{d^2}{dt^2} T_n(t) \right] = Y_p(x) \hat{P}(x)f(t) \quad (25)$$

Integrate with respect to length.

$$\begin{aligned}
& \int_0^L \left\{ EI \beta_n^4 \left[\sum_{n=1}^m T_n(t) Y_n(x) Y_p(x) \right] + \rho \left[\sum_{n=1}^m Y_n(x) Y_p(x) \frac{d^2}{dt^2} T_n(t) \right] \right\} dx \\
& = \int_0^L Y_p(x) \hat{P}(x) f(t) dx
\end{aligned} \tag{26}$$

$$\begin{aligned}
& EI \beta_n^4 \int_0^L \left[\sum_{n=1}^m T_n(t) Y_n(x) Y_p(x) \right] dx + \rho \int_0^L \left[\sum_{n=1}^m Y_n(x) Y_p(x) \frac{d^2}{dt^2} T_n(t) \right] dx \\
& = f(t) \int_0^L Y_p(x) \hat{P}(x) dx
\end{aligned} \tag{27}$$

$$\begin{aligned}
& EI \beta_n^4 \sum_{n=1}^m \left\{ T_n(t) \int_0^L Y_n(x) Y_p(x) dx \right\} + \rho \sum_{n=1}^m \left\{ \frac{d^2}{dt^2} T_n(t) \int_0^L Y_n(x) Y_p(x) dx \right\} \\
& = f(t) \int_0^L Y_p(x) \hat{P}(x) dx
\end{aligned} \tag{28}$$

$$\begin{aligned}
& \frac{EI \beta_n^4}{\rho} \sum_{n=1}^m \left\{ T_n(t) \int_0^L \rho Y_n(x) Y_p(x) dx \right\} + \sum_{n=1}^m \left\{ \frac{d^2}{dt^2} T_n(t) \int_0^L \rho Y_n(x) Y_p(x) dx \right\} \\
& = f(t) \int_0^L Y_p(x) \hat{P}(x) dx
\end{aligned} \tag{29}$$

The eigenvectors are orthogonal such that

$$\int_0^L \rho Y_n(x) Y_p(x) dx = 0 \quad \text{for } n \neq p \tag{30}$$

$$\int_0^L \rho Y_n(x) Y_p(x) dx = 1 \quad \text{for } n = p \tag{31}$$

$$\frac{d^2}{dt^2}T_n(t) + \frac{EI\beta_n^4}{\rho}T_n(t) = f(t)\int_0^L Y_n(x)\hat{P}(x)dx \quad (32)$$

$$\omega_n = \beta_n^2 \sqrt{\frac{EI}{\rho}} \quad (33)$$

$$\omega_n^2 = \frac{EI}{\rho} \beta_n^4 \quad (34)$$

$$\frac{d^2}{dt^2}T_n(t) + \omega_n^2 T_n(t) = f(t)\int_0^L Y_n(x)\hat{P}(x)dx \quad (35)$$

Add a damping term.

$$\ddot{T}_n(t) + 2\xi_n\omega_n\dot{T}_n(t) + \omega_n^2 T_n(t) = f(t)\int_0^L Y_n(x)\hat{P}(x)dx \quad (36)$$

Steady-State Solution

Take a Fourier transform of both sides of (36).

$$\int_{-\infty}^{\infty} \left\{ \ddot{T}_n(t) + 2\xi_n\omega_n\dot{T}_n(t) + \omega_n^2 T_n(t) \right\} \exp(-j\omega t) dt = \int_{-\infty}^{\infty} f(t) \int_0^L Y_n(x)\hat{P}(x) dx dt \quad (37)$$

$$\begin{aligned} \int_{-\infty}^{\infty} \ddot{T}_n(t) \exp(-j\omega t) dt + 2\xi_n\omega_n \int_{-\infty}^{\infty} \dot{T}_n(t) \exp(-j\omega t) dt + \omega_n^2 \int_{-\infty}^{\infty} T_n(t) \exp(-j\omega t) dt \\ = \left\{ \int_0^L Y_n(x)\hat{P}(x) dx \right\} \left\{ \int_{-\infty}^{\infty} f(t) \exp(-j\omega t) dt \right\} \end{aligned} \quad (38)$$

Note that

$$\int_{-\infty}^{\infty} \dot{T}_n(t) \exp(-j\omega t) dt = j\omega \int_{-\infty}^{\infty} T_n(t) \exp(-j\omega t) dt \quad (39)$$

$$\int_{-\infty}^{\infty} \ddot{T}_n(t) \exp(-j\omega t) dt = -\omega^2 \int_{-\infty}^{\infty} T_n(t) \exp(-j\omega t) dt \quad (40)$$

$$\begin{aligned} & -\omega^2 \int_{-\infty}^{\infty} T_n(t) \exp(-j\omega t) dt + j2\xi_n \omega_n \omega \int_{-\infty}^{\infty} T_n(t) \exp(-j\omega t) dt + \omega_n^2 \int_{-\infty}^{\infty} T_n(t) \exp(-j\omega t) dt \\ & = \left\{ \int_0^L Y_n(x) \hat{P}(x) dx \right\} \left\{ \int_{-\infty}^{\infty} f(t) \exp(-j\omega t) dt \right\} \end{aligned} \quad (41)$$

$$\left[(\omega_n^2 - \omega^2) + j2\xi_n \omega_n \omega \right] \int_{-\infty}^{\infty} T_n(t) \exp(-j\omega t) dt = \left\{ \int_0^L Y_n(x) \hat{P}(x) dx \right\} \left\{ \int_{-\infty}^{\infty} f(t) \exp(-j\omega t) dt \right\} \quad (42)$$

$$\hat{T}_n(\omega) = \int_{-\infty}^{\infty} T_n(t) \exp(-j\omega t) dt \quad (43)$$

$$F(\omega) = \int_{-\infty}^{\infty} f(t) \exp(-j\omega t) dt \quad (44)$$

$$\left[(\omega_n^2 - \omega^2) + j2\xi_n \omega_n \omega \right] \hat{T}_n(\omega) = \left\{ \int_0^L Y_n(x) \hat{P}(x) dx \right\} F(\omega) \quad (45)$$

$$\hat{T}_n(\omega) = F(\omega) \frac{\int_0^L Y_n(x) \hat{P}(x) dx}{\left(\omega_n^2 - \omega^2\right) + j2\xi_n \omega \omega_n} \quad (46)$$

$$Y(x, \omega) = \sum_{n=1}^m Y_n(x) \hat{T}_n(\omega) \quad (47)$$

The Fourier transform of the displacement is

$$Y(x, \omega) = F(\omega) \sum_{n=1}^m \frac{Y_n(x) \int_0^L Y_n(x) \hat{P}(x) dx}{\left(\omega_n^2 - \omega^2\right) + j2\xi_n \omega \omega_n} \quad (48)$$

The frequency response function relating the displacement to the distributed force is

$$\frac{Y(x, \omega)}{F(\omega)} = \sum_{n=1}^m \frac{Y_n(x) \int_0^L Y_n(x) \hat{P}(x) dx}{\left(\omega_n^2 - \omega^2\right) + j2\xi_n \omega \omega_n} \quad (49)$$

The bending moment transfer function is

$$\frac{M(x, \omega)}{F(\omega)} = \frac{EI Y''(x, \omega)}{F(\omega)} = \frac{EI}{\rho} \sum_{n=1}^m \left\{ \frac{\Gamma_n Y_n''(x)}{\left(\omega_n^2 - \omega^2\right) + j2\xi_n \omega \omega_n} \right\} \quad (50)$$

The bending stress transfer function is

$$\frac{\sigma(x, \omega)}{F(\omega)} = \left(\frac{c}{I} \right) \frac{M(x, \omega)}{F(\omega)} \quad (51)$$

where c is the distance from the neutral axis

References

1. T. Irvine, Bending Frequencies of Beams, Rod, and Pipes, Revision P, Vibrationdata, 2011.
2. T. Irvine, Steady-State Vibration Response of a Cantilever Beam Subjected to Base Excitation, Rev A, Vibrationdata, 2009.

APPENDIX A

Special Case

$$\frac{Y(x, \omega)}{F(\omega)} = \sum_{n=1}^m \frac{Y_n(x) \int_0^L Y_n(x) \hat{P}(x) dx}{(\omega_n^2 - \omega^2) + j 2 \xi_n \omega_n \omega} \quad (A-1)$$

$$Y_n(x) = \frac{1}{\sqrt{\rho L}} \{ [\cosh(\beta_n x) - \cos(\beta_n x)] - \sigma_n [\sinh(\beta_n x) - \sin(\beta_n x)] \} \quad (A-2)$$

Now assume that

$$\hat{P}(x) = \sqrt{\rho L} Y_1(x) \quad (A-3)$$

$$\frac{Y(x, \omega)}{F(\omega)} = \sqrt{\rho L} \sum_{n=1}^m \frac{Y_n(x) \int_0^L Y_n(x) Y_1(x) dx}{(\omega_n^2 - \omega^2) + j 2 \xi_n \omega_n \omega} \quad (A-4)$$

Note that the orthogonality condition yields

$$\int_0^L Y_n(x) Y_1(x) dx = \begin{cases} L, & \text{for } n = 1 \\ 0, & \text{for } n = 2, 3, 4, \dots \end{cases} \quad (A-5)$$

The displacement transfer function is

$$\frac{Y(x, \omega)}{F(\omega)} = \frac{1}{\rho} \left\{ \frac{[\cosh(\beta_n x) - \cos(\beta_n x)] - \sigma_n [\sinh(\beta_n x) - \sin(\beta_n x)]}{(\omega_1^2 - \omega^2) + j 2 \xi_1 \omega_1 \omega} \right\} \quad (A-6)$$

The bending moment transfer function is

$$\frac{M(x, \omega)}{F(\omega)} = \frac{EI Y''(x, \omega)}{F(\omega)} = \frac{EI \beta_n^2}{\rho} \left\{ \frac{[\cosh(\beta_n x) + \cos(\beta_n x)] - \sigma_n [\sinh(\beta_n x) + \sin(\beta_n x)]}{(\omega_1^2 - \omega^2) + j 2 \xi_1 \omega_1 \omega} \right\} \quad (A-7)$$

The bending stress transfer function is

$$\frac{\sigma(x, \omega)}{F(\omega)} = \left(\frac{c}{I} \right) \frac{M(x, \omega)}{F(\omega)} \quad (A-8)$$

APPENDIX B

Example

Consider a beam with the following properties:

Cross-Section	Rectangular
Boundary Conditions	Fixed-Fixed
Material	Aluminum

Thickness	T	=	0.125 inch
Width	W	=	1.0 inch
Length	L	=	27.5 inch
Cross-Section Area	A	=	0.125 in ²
Area Moment of Inertia	I	=	0.000163 in ⁴
Elastic Modulus	E	=	10E+06 lbf/in ²
Stiffness	EI	=	1628 lbf in ²
Mass per Volume	ρ_v	=	0.1 lbm / in ³ (0.000259 lbf sec ² /in ⁴)
Mass per Length	ρ	=	0.0125 lbm / in (0.00003237 lbf sec ² /in ⁴)
Mass	ρL	=	0.3438 lbm (0.0008906 lbf sec ² /in)
Viscous Damping Ratio	ξ	=	0.05

The normal modes and frequency response function analysis are performed via a Matlab script.

The normal modes results are:

Table B-1. Natural Frequency Results, Fixed-Fixed, Beam		
Mode	fn (Hz)	Participation Factor
1	33.38	0.02479
2	92.02	0
3	180.4	0.01086
4	298.2	0
5	445.4	0.006908

Note that the mode shape and participation factors are considered as dimensionless, but they must be consistent with respect to one another.

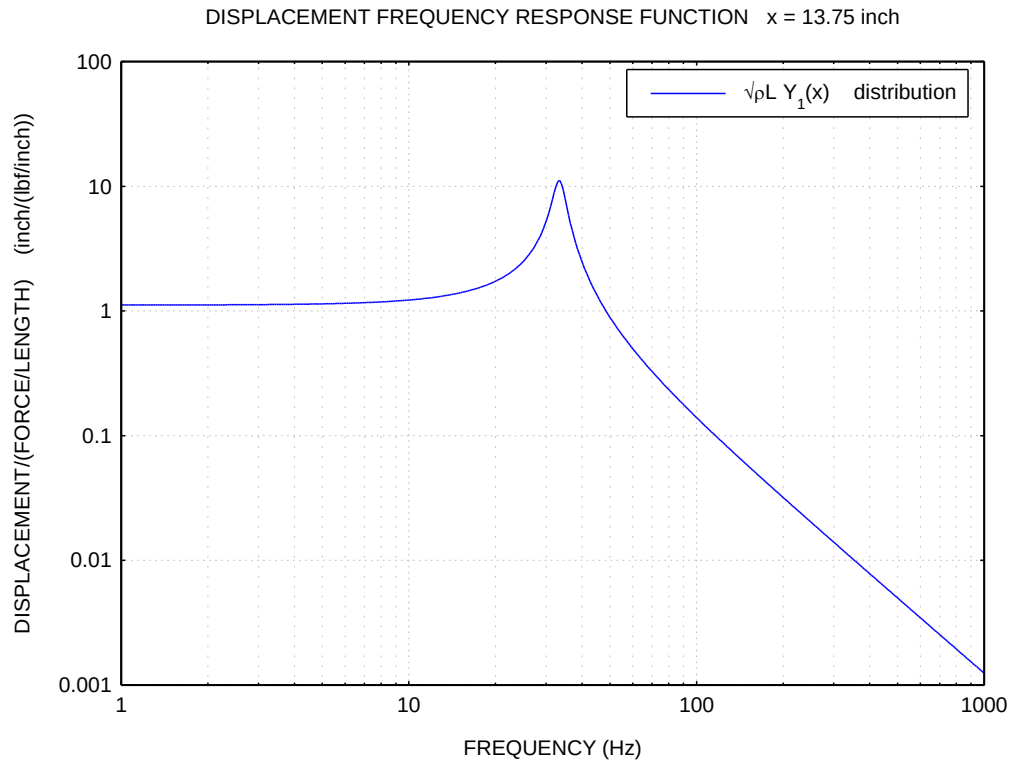


Figure B-1.

Now consider that the pressure field has the spatial distribution:

$$\hat{P}(x) = \sqrt{\rho L} Y_1(x) \quad (B-1)$$

The resulting transfer function magnitude is shown in Figure B-1.

The maximum displacement response is: 11.13 [in/(lbf/in)] at 33.42 Hz

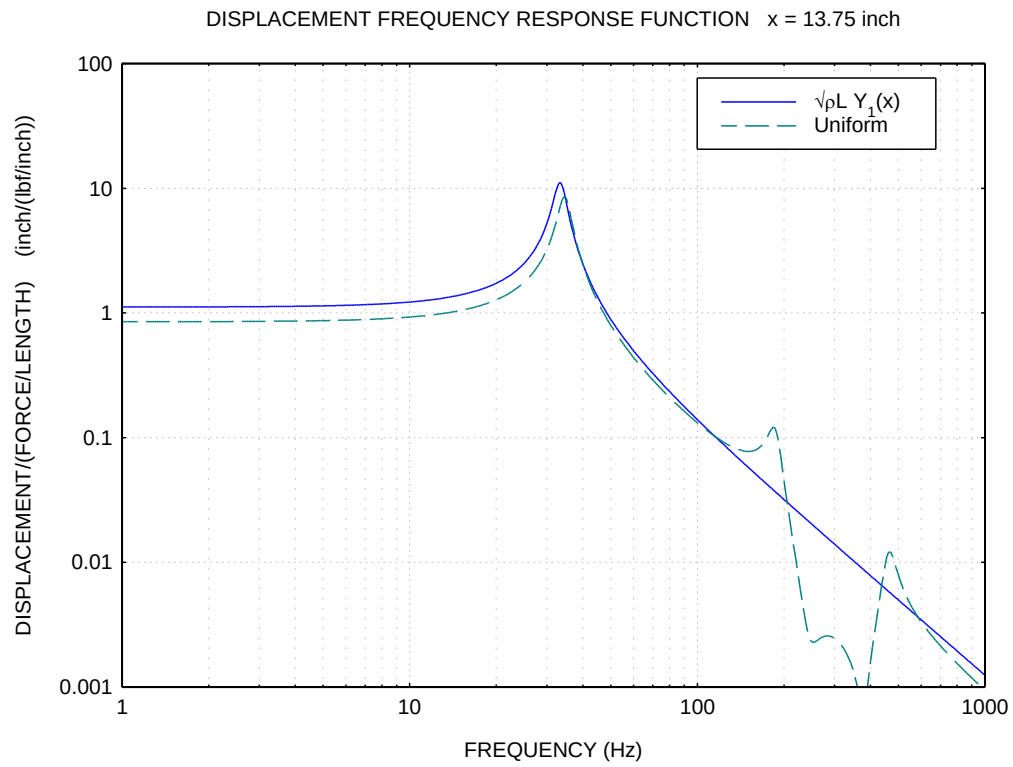


Figure B-2.

The displacement frequency response functions for two pressure distributions are shown in Figure B-2.

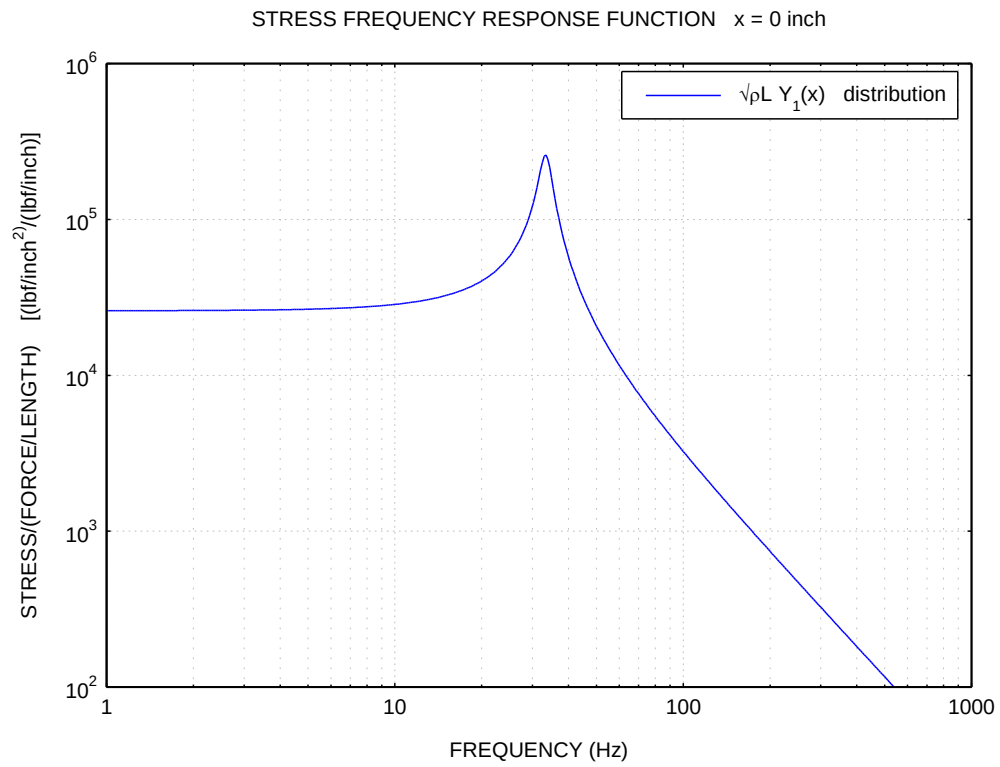


Figure B-3.

The maximum stress response is: 2.59×10^5 [(lbf/in²)/(lbf/in)] at 33.42 Hz