## STEADY-STATE VIBRATION RESPONSE OF A SIMPLY-SUPPORTED BEAM SUBJECTED TO A UNIFORM DISTIBUTED APPLIED FORCE Revision C

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The simply-supported beam in Figure 1 is subjected to a uniform, distributed applied force.



Figure 1.

The following equations are taken from References 1 and 2.

The governing differential equation is

$$EI\frac{\partial^4 y}{\partial x^4} + \rho \frac{\partial^2 y}{\partial t^2} = P(x,t)$$
(1)

where

- E is the modulus of elasticity
- I is the area moment of inertia
- L is the length
- $\rho$  is the mass density (mass/length)
- P is the applied force per length

Now assume that the force is uniform such that

$$W(t) = P(x, t)$$
<sup>(2)</sup>

The differential equation becomes

$$EI\frac{\partial^4 y}{\partial x^4} + \rho \frac{\partial^2 y}{\partial t^2} = W(t)$$
(3)

The natural frequency term  $\omega_n$  is

$$\omega_n = \beta_n^2 \sqrt{\frac{EI}{\rho}}$$
(4)

$$\beta_n = \left[\frac{n\pi}{L}\right] \tag{5}$$

The natural frequency is

$$\omega_{n} = \left[\frac{n\pi}{L}\right]^{2} \sqrt{\frac{EI}{\rho}}, n = 1, 2, 3, \dots$$
(6)

$$f_{n} = \left[\frac{1}{2\pi}\right] \left[\frac{n\pi}{L}\right]^{2} \sqrt{\frac{EI}{\rho}}, \quad n = 1, 2, 3, \dots$$
(7)

The mass-normalized mode shapes and derivatives are

$$Y_{n}(x) = \sqrt{\frac{2}{\rho L}} \sin(n\pi x/L)$$
(8)

$$Y_{n}'(x) = \frac{n\pi}{L} \sqrt{\frac{2}{\rho L}} \cos(n\pi x/L)$$
(9)

$$Y_{n}''(x) = -\left(\frac{n\pi}{L}\right)^{2} \sqrt{\frac{2}{\rho L}} \sin(n\pi x/L)$$
(10)

The participation factors for constant mass density are

$$\Gamma_n = \rho \int_0^L Y_n(x) dx \tag{11}$$

$$\Gamma_{n} = -\sqrt{2\rho L} \left[ \frac{1}{n\pi} \right] \left[ \cos(n\pi) - 1 \right] , n=1, 2, 3, \dots$$
 (12)

The displacement response  $Y(x, \omega)$  to the applied force is

$$Y(x,\omega) = \frac{1}{\rho} W(\omega) \sum_{n=1}^{m} \left\{ \frac{\Gamma_n Y_n(x)}{\left(\omega_n^2 - \omega^2\right) + j2\xi_n \omega \omega_n} \right\}$$
(13)

The transfer function is

$$\frac{\mathbf{Y}(\mathbf{x},\boldsymbol{\omega})}{\mathbf{W}(\boldsymbol{\omega})} = \frac{1}{\rho} \sum_{n=1}^{m} \left\{ \frac{\Gamma_n \mathbf{Y}_n(\mathbf{x})}{\left(\boldsymbol{\omega}_n^2 - \boldsymbol{\omega}^2\right) + j2\xi_n \boldsymbol{\omega} \boldsymbol{\omega}_n} \right\}$$
(14)

The bending moment  $M(x, \omega)$  is

$$M(x,\omega) = EI \frac{\partial^2}{\partial x^2} Y(x,\omega)$$
(15)

$$M(x,\omega) = \frac{EI}{\rho} W(\omega) \sum_{n=1}^{m} \left\{ \frac{\Gamma_n Y_n''(x)}{\left(\omega_n^2 - \omega^2\right) + j2\xi_n \omega \omega_n} \right\}$$
(16)

The bending stress is

$$\sigma(\mathbf{x},\omega) = \frac{\hat{c}}{I} \mathbf{M}(\mathbf{x},\omega) \tag{17}$$

where  $\hat{c}$  is the distance to the neutral axis.

$$\sigma(\mathbf{x},\omega) = \frac{\hat{c}}{I} \frac{EI}{\rho} W(\omega) \sum_{n=1}^{m} \left\{ \frac{\Gamma_n Y_n''(\mathbf{x})}{\left(\omega_n^2 - \omega^2\right) + j2\xi_n \omega \omega_n} \right\}$$
(18)

$$\sigma(\mathbf{x},\omega) = \frac{\hat{c}E}{\rho} W(\omega) \sum_{n=1}^{m} \left\{ \frac{\Gamma_n Y_n''(\mathbf{x})}{\left(\omega_n^2 - \omega^2\right) + j2\xi_n \omega \omega_n} \right\}$$
(19)

The bending stress transfer function is

$$\frac{\sigma(\mathbf{x},\omega)}{W(\omega)} = \frac{\hat{c} E}{\rho} \sum_{n=1}^{m} \left\{ \frac{\Gamma_n Y_n''(\mathbf{x})}{\left(\omega_n^2 - \omega^2\right) + j2\xi_n \omega \omega_n} \right\}$$
(20)

The shear force  $V(x, \omega)$  is

$$V(x,\omega) = EI \frac{\partial^3}{\partial x^3} Y(x,\omega)$$
(21)

$$V(x,\omega) = \frac{EI}{\rho} W(\omega) \sum_{n=1}^{m} \left\{ \frac{\Gamma_n Y_n''(x)}{\left(\omega_n^2 - \omega^2\right) + j2\xi_n \omega \omega_n} \right\}$$
(22)

The average shear stress  $\tau_{ave}\,$  is

$$\tau_{\text{ave}} = \frac{V(x,\omega)}{A} \tag{23}$$

where A is the cross-section area

The maximum shear stress  $\tau_{max}$  occurs at the neutral axis and is

$$\tau_{\max} = \alpha \tau_{ave} \tag{24}$$

where

Cross-section	α
Solid Rectangle	3/2
Solid Cylinder	4/3
Pipe	2
I-beam	A / A <sub>web</sub>

## References

- 1. T. Irvine, Bending Frequencies of Beams, Rod, and Pipes, Revision P, Vibrationdata, 2011.
- 2. T. Irvine, Steady-State Vibration Response of a Cantilever Beam Subjected to Base Excitation, Rev A, Vibrationdata, 2009.

## APPENDIX A

## Example

Consider a beam with the following properties:

Cross-Section	Rectangular
Boundary Conditions	Simply Supported at Each End
Material	Aluminum

Thickness	Т	=	0.125 inch
Width	W	=	1.0 inch
Length	L	=	27.5 inch
Cross-Section Area	А	=	0.125 in^2
Area Moment of Inertia	Ι	=	0.000163 in^4
Elastic Modulus	Е	=	1630 lbf/in^2
Stiffness	EI	=	1.042+05 lbf/in^2
Mass per Volume	$\rho_{v}$	=	0.1 lbm / in^3 ( 0.000259 lbf sec^2/in^4 )
Mass per Length	ρ	=	0.0125 lbm / in ( 0.00003237 lbf sec^2/in^4 )
Mass	ρL	=	0.3438 lbm ( 0.0008906 lbf sec^2/in)
Viscous Damping Ratio	ξ	=	0.05

The normal modes and frequency response function analysis are performed via a Matlab script.

The normal modes results are:

Table 1. Natural Frequency Results, BeamSimply-Supported at Each End				
Mode	fn (Hz)	Participation Factor		
1	14.7	0.02687		
2	58.9	0		
3	132.5	0.008956		
4	235.6	0		
5	368.1	0.005373		
6	530.1	0		

Note that the mode shape and participation factors are considered as dimensionless, but they must be consistent with respect to one another.

The resulting transfer function magnitude is shown in Figure A-1.



Figure A-1.

The maximum displacement response is: 46.0 [in/(lbf/in)] at 14.7 Hz



Figure A-2.







The maximum shear force response is: 112 [lbf/(lbf/in)] at 14.7 Hz