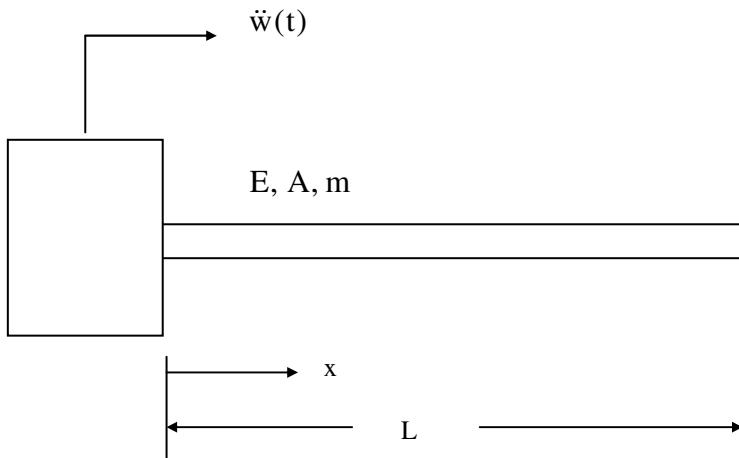


ROD RESPONSE TO LONGITUDINAL BASE EXCITATION,
STEADY-STATE AND TRANSIENT
Revision B

By Tom Irvine
Email: tomirvine@aol.com

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Consider a thin rod subjected to base excitation.



The variables are

Cross-section area	A
Elastic Modulus	E
Length	L
Mass per Volume	ρ
Mass per Length	m
Relative Displacement	$u(x,t)$
Base Acceleration	$\ddot{w}(t)$
Base Excitation Frequency (rad/sec)	ω
Natural Frequency (rad/sec)	ω_n
Viscous Damping Ratio	ξ

Consider a rod with uniform mass density and constant cross-section. The rod is driven by base excitation. The governing equation is

$$EA \frac{\partial^2 u}{\partial x^2} - m \frac{\partial^2 u}{\partial t^2} = m \frac{\partial^2 w}{\partial t^2} \quad (1)$$

The term on the right-hand-side is the inertial force per unit length.

Assume separation of variables.

$$u(x, t) = \sum_{n=1}^m U_n(x) T_n(t) \quad (2)$$

By substitution,

$$EA \frac{\partial^2}{\partial x^2} \left\{ \sum_{n=1}^m U_n(x) T_n(t) \right\} - m \frac{\partial^2}{\partial t^2} \left\{ \sum_{n=1}^m U_n(x) T_n(t) \right\} = m \frac{d^2 w}{dt^2} \quad (3)$$

$$EA \left\{ \sum_{n=1}^m \left[\frac{\partial^2}{\partial x^2} U_n(x) \right] T_n(t) \right\} - m \left\{ \sum_{n=1}^m U_n(x) \left[\frac{\partial^2}{\partial t^2} T_n(t) \right] \right\} = m \frac{d^2 w}{dt^2} \quad (4)$$

Change to ordinary derivatives.

$$EA \left\{ \sum_{n=1}^m \left[\frac{d^2}{dx^2} U_n(x) \right] T_n(t) \right\} - m \left\{ \sum_{n=1}^m U_n(x) \left[\frac{d^2}{dt^2} T_n(t) \right] \right\} = m \frac{d^2 w}{dt^2} \quad (5)$$

Note from Reference 1 that

$$\frac{d^2}{dx^2} U_n(x) = \frac{-\omega_n^2}{c^2} U_n(x) \quad (6)$$

By substitution

$$-EA \left\{ \sum_{n=1}^m \frac{\omega_n^2}{c^2} U_n(x) T_n(t) \right\} - m \left\{ \sum_{n=1}^m U_n(x) \left[\frac{d^2}{dt^2} T_n(t) \right] \right\} = m \frac{d^2 w}{dt^2} \quad (7)$$

$$-EA \frac{\omega_n^2}{c^2} \left\{ \sum_{n=1}^m U_n(x) T_n(t) \right\} - m \left\{ \sum_{n=1}^m U_n(x) \left[\frac{d^2}{dt^2} T_n(t) \right] \right\} = m \frac{d^2 w}{dt^2} \quad (8)$$

Multiply each term by $U_p(x)$.

$$\begin{aligned} & -EA \frac{\omega_n^2}{c^2} \left\{ \sum_{n=1}^m U_n(x) U_p(x) T_n(t) \right\} - m \left\{ \sum_{n=1}^m U_n(x) U_p(x) \left[\frac{d^2}{dt^2} T_n(t) \right] \right\} \\ &= m U_p(x) \frac{d^2 w}{dt^2} \end{aligned} \quad (9)$$

Integrate with respect to length.

$$\begin{aligned} & \int_0^L \left\{ -EA \frac{\omega_n^2}{c^2} \left\{ \sum_{n=1}^m U_n(x) U_p(x) T_n(t) \right\} \right\} dx \\ & \int_0^L \left\{ -m \left\{ \sum_{n=1}^m U_n(x) U_p(x) \left[\frac{d^2}{dt^2} T_n(t) \right] \right\} \right\} dx \\ &= \int_0^L \left\{ -m U_p(x) \frac{d^2 w}{dt^2} \right\} dx \end{aligned}$$

(10)

$$\left\{ -EA \frac{\omega_n^2}{c^2} T_n(t) \right\} \left\{ \sum_{n=1}^m \int_0^L U_n(x) U_p(x) dx \right\} - m \left[\frac{d^2}{dt^2} T_n(t) \right] \left\{ \sum_{n=1}^m \int_0^L U_n(x) U_p(x) dx \right\} \\ = m \frac{d^2 w}{dt^2} \int_0^L \{ U_p(x) \} dx \quad (11)$$

The eigenvectors are orthogonal such that

$$m \int_0^L U_n(x) U_p(x) dx = 0 \quad \text{for } n \neq p \quad (12)$$

$$m \int_0^L U_n(x) U_p(x) dx = 1 \quad \text{for } n = p \quad (13)$$

Thus,

$$\left\{ -EA \frac{\omega_n^2}{c^2} T_n(t) \right\} - m \left[\frac{d^2}{dt^2} T_n(t) \right] = m \frac{d^2 w}{dt^2} \int_0^L \{ U_n(x) \} dx \quad (14)$$

$$-\frac{d^2}{dt^2} T_n(t) - \left[\frac{EA}{m} \right] \frac{\omega_n^2}{c^2} T_n(t) = \frac{d^2 w}{dt^2} \int_0^L \{ U_n(x) \} dx \quad (15)$$

$$-\frac{d^2}{dt^2} T_n(t) - \omega_n^2 T_n(t) = \frac{d^2 w}{dt^2} \int_0^L \{ U_n(x) \} dx \quad (16)$$

$$\frac{d^2}{dt^2} T_n(t) + \omega_n^2 T_n(t) = -\frac{d^2 w}{dt^2} \int_0^L \{U_n(x)\} dx \quad (17)$$

Define a participation factor.

$$\Gamma_n = \int_0^L \{U_n(x)\} dx \quad (18)$$

By substitution,

$$\frac{d^2}{dt^2} T_n(t) + \omega_n^2 T_n(t) = -\Gamma_n \frac{d^2 w}{dt^2} \quad (19)$$

Add a modal damping term.

$$\frac{d^2}{dt^2} T_n(t) + 2\xi_n \omega_n \frac{d}{dt} T_n(t) + \omega_n^2 T_n(t) = -\Gamma_n \frac{d^2 w}{dt^2} \quad (20)$$

Change notation.

$$\ddot{T}_n(t) + 2\xi_n \omega_n \dot{T}_n(t) + \omega_n^2 T_n(t) = -\Gamma_n \ddot{w}(t) \quad (21)$$

Take the Fourier transform of each side

$$\int_{-\infty}^{\infty} \left\{ \ddot{T}_n(t) + 2\xi_n \omega_n \dot{T}_n(t) + \omega_n^2 T_n(t) \right\} \exp(j\omega t) dt = -\Gamma_n \int_{-\infty}^{\infty} \ddot{w}(t) \exp(j\omega t) dt \quad (22)$$

$$\begin{aligned}
& \int_{-\infty}^{\infty} \ddot{T}_n(t) \exp(j\omega t) dt + 2\xi_n \omega_n \int_{-\infty}^{\infty} \dot{T}_n(t) \exp(j\omega t) dt + \omega_n^2 \int_{-\infty}^{\infty} T_n(t) \exp(j\omega t) dt \\
&= -\Gamma_n \int_{-\infty}^{\infty} \ddot{w}(t) \exp(j\omega t) dt
\end{aligned} \tag{23}$$

Note that

$$\int_{-\infty}^{\infty} \dot{T}_n(t) \exp(j\omega t) dt = j\omega \int_{-\infty}^{\infty} T_n(t) \exp(j\omega t) dt \tag{24}$$

$$\int_{-\infty}^{\infty} \ddot{T}_n(t) \exp(j\omega t) dt = -\omega^2 \int_{-\infty}^{\infty} T_n(t) \exp(j\omega t) dt \tag{25}$$

$$\begin{aligned}
& -\omega^2 \int_{-\infty}^{\infty} T_n(t) \exp(j\omega t) dt + j2\xi_n \omega_n \omega \int_{-\infty}^{\infty} T_n(t) \exp(j\omega t) dt + \omega_n^2 \int_{-\infty}^{\infty} T_n(t) \exp(j\omega t) dt \\
&= -\Gamma_n \int_{-\infty}^{\infty} \ddot{w}(t) \exp(j\omega t) dt
\end{aligned} \tag{26}$$

$$\left\{ \left(\omega_n^2 - \omega^2 \right) + j2\xi_n \omega_n \omega \right\} \int_{-\infty}^{\infty} T_n(t) \exp(j\omega t) dt = -\Gamma_n \int_{-\infty}^{\infty} \ddot{w}(t) \exp(j\omega t) dt \tag{27}$$

Let

$$\hat{T}_n(\omega) = \int_{-\infty}^{\infty} T_n(t) \exp(j\omega t) dt \tag{28}$$

$$\ddot{W}(\omega) = \int_{-\infty}^{\infty} \ddot{w}(t) \exp(j\omega t) dt \tag{29}$$

By substitution,

$$\left\{ \left(\omega_n^2 - \omega^2 \right) + j2\xi_n \omega_n \omega \right\} \hat{T}_n(\omega) = -\Gamma_n \ddot{W}(\omega) \quad (30)$$

$$\hat{T}_n(\omega) = \frac{-\Gamma_n \ddot{W}(\omega)}{\left\{ \left(\omega_n^2 - \omega^2 \right) + j2\xi_n \omega_n \omega \right\}} \quad (31)$$

Recall

$$u(x, t) = \sum_{n=1}^m U_n(x) T_n(t) \quad (32)$$

The Fourier transform of the relative displacement is

$$\hat{U}(x, \omega) = \sum_{n=1}^m U_n(x) \hat{T}_n(\omega) \quad (33)$$

$$\hat{U}(x, \omega) = \sum_{n=1}^m U_n(x) \frac{-\Gamma_n \ddot{W}(\omega)}{\left\{ \left(\omega_n^2 - \omega^2 \right) + j2\xi_n \omega_n \omega \right\}} \quad (34)$$

$$\hat{U}(x, \omega) = \ddot{W}(\omega) \sum_{n=1}^m U_n(x) \frac{-\Gamma_n}{\left\{ \left(\omega_n^2 - \omega^2 \right) + j2\xi_n \omega_n \omega \right\}} \quad (35)$$

The ω term is given a subscript n because there are multiple roots. The natural frequencies for a fixed-free rod are

$$\omega_n = \left(\frac{2n-1}{2} \right) \pi \frac{c}{L}, \quad n = 1, 2, 3, \dots \quad (36)$$

The displacement function for the fixed-free rod is

$$U_n(x) = d_n \sin\left(\frac{\omega_n x}{c}\right) \quad (37)$$

$$U_n(x) = d_n \sin\left(\frac{(2n-1)\pi x}{2L}\right) \quad (38)$$

Need to normalize with respect to mass

$$m \int_0^L U_n(x) U_p(x) dx = 1 \quad \text{for } n = p \quad (39)$$

$$m \int_0^L d_n^2 \sin^2\left(\frac{\omega_n x}{c}\right) dx = 1 \quad (40)$$

$$m d_n^2 \int_0^L \left[\frac{1}{2} - \frac{1}{2} \cos\left(\frac{2\omega_n x}{c}\right) \right] dx = 1 \quad (41)$$

Recall

$$\omega_n = \left(\frac{2n-1}{2} \right) \pi \frac{c}{L} \quad (42)$$

$$m d_n^2 \int_0^L \left[\frac{1}{2} - \frac{1}{2} \cos \left((2n-1) \frac{\pi x}{L} \right) \right] dx = 1 \quad (43)$$

$$\frac{1}{2} m d_n^2 \left\{ x - \left[\frac{L}{(2n-1)\pi} \right] \sin \left((2n-1) \frac{\pi x}{L} \right) \right\} \Big|_0^L = 1 \quad (44)$$

$$\frac{1}{2} m d_n^2 L = 1 \quad (45)$$

$$d_n^2 = \frac{2}{mL} \quad (46)$$

$$d_n = \sqrt{\frac{2}{mL}} \quad (47)$$

The participation factor is

$$\Gamma_n = m \int_0^L U_n(x) dx \quad (48)$$

$$\Gamma_n = m \int_0^L \left\{ d_n \sin \left(\frac{\omega_n x}{c} \right) \right\} dx \quad (49)$$

$$\Gamma_n = m d_n \int_0^L \left\{ \sin \left(\frac{\omega_n x}{c} \right) \right\} dx \quad (50)$$

$$\Gamma_n = - \left(\frac{m c d_n}{\omega_n} \right) \left\{ \cos \left(\frac{\omega_n x}{c} \right) \Big|_0^L \right\} \quad (51)$$

$$\Gamma_n = -\left(\frac{mc d_n}{\omega_n}\right) \left\{ \cos\left(\left(\frac{2n-1}{2}\right)\frac{\pi x}{L}\right) \Big|_0^L \right\} \quad (52)$$

$$\Gamma_n = \left(\frac{mc d_n}{\omega_n}\right) \quad (53)$$

$$d_n = \sqrt{\frac{2}{mL}} \quad (54)$$

$$\Gamma_n = \left(\frac{mc}{\omega_n} \sqrt{\frac{2}{mL}}\right) \quad (55)$$

$$\Gamma_n = \left(\frac{c}{\omega_n} \sqrt{\frac{2m}{L}}\right) \quad (56)$$

Again,

$$\omega_n = \left(\frac{2n-1}{2}\right)\pi \frac{c}{L}, \quad n = 1, 2, 3, \dots \quad (57)$$

By substitution,

$$\Gamma_n = \left(\frac{c}{\left(\left(\frac{2n-1}{2}\right)\pi \frac{c}{L}\right)} \sqrt{\frac{2m}{L}}\right) \quad (58)$$

$$\Gamma_n = \left(\frac{2L}{((2n-1)\pi)} \sqrt{\frac{2m}{L}}\right) \quad (59)$$

$$\Gamma_n = \left(\frac{2}{((2n-1)\pi)} \sqrt{2mL} \right) \quad (60)$$

As a summary,

Mode	Natural Frequency ω_n	d_n	Γ_n
1	$0.5\pi c/L$	$\sqrt{2/(mL)}$	$\frac{2}{\pi}\sqrt{2mL}$
2	$1.5\pi c/L$	$\sqrt{2/(mL)}$	$\frac{2}{3\pi}\sqrt{2mL}$
3	$2.5\pi c/L$	$\sqrt{2/(mL)}$	$\frac{2}{5\pi}\sqrt{2mL}$

The relative displacement is found using the method in Reference 2.

$$U(x, \omega) = \ddot{W}(\omega) \sum_{n=1}^p \left[\frac{-\Gamma_n \hat{U}_n(x)}{(\omega_n^2 - \omega^2) + j(2\xi\omega\omega_n)} \right] \quad (61)$$

where p is the total number of modes included in the analysis.

Let

$$H_{rn}(x, \omega) = \frac{-\Gamma_n \hat{U}_n(x)}{(\omega_n^2 - \omega^2) + j(2\xi\omega\omega_n)} \quad (62)$$

Thus

$$U(x, \omega) = \ddot{W}(\omega) \sum_{n=1}^p [H_{rn}(x, \omega)] \quad (63)$$

Again,

$$\hat{U}_n(x) = \sqrt{\frac{2}{mL}} \sin\left(\frac{\omega_n x}{c}\right) \quad (64)$$

The strain is

$$\frac{\partial}{\partial x} U(x, \omega) = \ddot{W}(\omega) \sum_{n=1}^p \left[\frac{-\Gamma_n \frac{d}{dx} \hat{U}_n(x)}{(\omega_n^2 - \omega^2) + j(2\xi\omega\omega_n)} \right] \quad (65)$$

where

$$\frac{d}{dx} \hat{U}_n(x) = \frac{\omega_n}{c} \sqrt{\frac{2}{mL}} \cos\left(\frac{\omega_n x}{c}\right) \quad (66)$$

The response absolute acceleration is

$$\ddot{U}(x, \omega) = \left\{ 1 + \sum_{n=1}^p \left[\frac{\omega^2 \Gamma_n \hat{U}_n(x)}{(\omega_n^2 - \omega^2) + j(2\xi\omega\omega_n)} \right] \right\} \ddot{W}(\omega) \quad (67)$$

Let

$$H_{an}(x, \omega) = \left[\frac{\omega^2 \Gamma_n \hat{U}_n(x)}{(\omega_n^2 - \omega^2) + j(2\xi\omega\omega_n)} \right] \quad (68)$$

Thus

$$\ddot{U}(x, \omega) = \left\{ 1 + \sum_{n=1}^p H_{an}(x, \omega) \right\} \ddot{W}(\omega) \quad (69)$$

The transient response is derived in Appendix A.

References

1. T. Irvine, Longitudinal Natural Frequencies of Rods and Response to Initial Conditions, Revision B, Vibrationdata, 2009.
2. T. Irvine, Steady-State Vibration Response of a Cantilever Beam Subjected to Base Excitation, Revision A, Vibrationdata, 2009.

APPENDIX A

Transient Response

Recall the modal transfer function for the relative displacement.

$$H_{rn}(x, \omega) = \frac{-\Gamma_n \hat{U}_n(x)}{(\omega_n^2 - \omega^2) + j(2\xi\omega\omega_n)} \quad (A-1)$$

The roots of the denominator are

$$\omega_d \pm j\xi\omega_n \quad (A-2)$$

where

$$\omega_d = \omega_n \sqrt{1 - \xi^2} \quad (A-3)$$

The partial fraction expansion is

$$\frac{-1}{(\omega_n^2 - \omega^2) + j(2\xi\omega\omega_n)} = \left\{ \frac{1}{2\omega_d} \right\} \left\{ \frac{1}{\omega + \omega_d + j\xi\omega_n} + \frac{-1}{\omega - \omega_d + j\xi\omega_n} \right\} \quad (A-4)$$

The impulse response function is

$$\hat{h}_{rn}(t) = \frac{1}{\omega_d} [\exp\{-\xi\omega_n t\}] [\sin \omega_d t] \quad , \quad t \geq 0 \quad (A-5)$$

The relative displacement response to an arbitrary acceleration $\ddot{w}(t)$ is

$$U(x, t) = - \sum_{n=1}^p \left\{ \Gamma_n \hat{U}_n(x) \int_0^t \hat{h}_{rn}(t-\tau) \ddot{w}(\tau) d\tau \right\} \quad (A-6)$$

For digital data,

$$U(x, t_i) = - \sum_{n=1}^p \left\{ \Gamma_n \hat{U}_n(x) \sum_{i=1}^q \hat{h}_{rn}(t_i - \tau_i) \ddot{w}(\tau_i) \Delta\tau \right\} \quad (A-7)$$

where q is the number of sample needed for the time to advance to t_i .

APPENDIX B

Indirect Verification of the Impulse Response Function

$$H_{rn}(x, \omega) = -\Gamma_n \hat{U}_n(x) \int_0^\infty \hat{h}_{rn}(t) \exp(-j\omega t) dt \quad (B-1)$$

$$H_{rn}(x, \omega) = -\Gamma_n \hat{U}_n(x) \int_0^\infty \frac{1}{\omega_d} [\exp(-\xi\omega_n t)] [\sin \omega_d t] \exp(-j\omega t) dt \quad (B-2)$$

$$H_{rn}(x, \omega) = \frac{-\Gamma_n \hat{U}_n(x)}{\omega_d} \int_0^\infty [\exp(-\xi\omega_n t)] [\sin \omega_d t] \exp(-j\omega t) dt \quad (B-3)$$

$$H_{rn}(x, \omega) =$$

$$\frac{-\Gamma_n \hat{U}_n(x)}{j2\omega_d} \int_0^\infty [\exp(-\xi\omega_n t)] [\exp(j\omega_d t) - \exp(-j\omega_d t)] \exp(-j\omega t) dt \quad (B-4)$$

$$H_{rn}(x, \omega) =$$

$$\frac{-\Gamma_n \hat{U}_n(x)}{j2\omega_d} \int_0^\infty [\exp(-\xi\omega_n t)] [\exp j(\omega_d - \omega)t - \exp j(\omega_d + \omega)t] dt \quad (B-5)$$

$$H_{rn}(x, \omega) =$$

$$\frac{-\Gamma_n \hat{U}_n(x)}{j2\omega_d} \int_0^\infty [\exp[-\xi\omega_n + j(\omega_d - \omega)]t - \exp[-\xi\omega_n + j(\omega_d + \omega)]t] dt \quad (B-6)$$

$$H_{rn}(x, \omega) =$$

$$\frac{-\Gamma_n \hat{U}_n(x)}{j2\omega_d} \int_0^\infty [\exp[-\xi\omega_n + j(\omega_d - \omega)]t - \exp[-\xi\omega_n + j(\omega_d + \omega)]t] dt$$
(B-7)

$$H_{rn}(x, \omega) =$$

$$\begin{aligned} & \frac{-\Gamma_n \hat{U}_n(x)}{j2\omega_d} \int_0^\infty [\exp[-\xi\omega_n + j(\omega_d - \omega)]t] dt \\ & + \frac{\Gamma_n \hat{U}_n(x)}{j2\omega_d} \int_0^\infty [\exp[-\xi\omega_n + j(\omega_d + \omega)]t] dt \end{aligned}$$
(B-8)

$$H_{rn}(x, \omega) =$$

$$\begin{aligned} & \frac{-\Gamma_n \hat{U}_n(x)}{j2\omega_d [-\xi\omega_n + j(\omega_d - \omega)]} \exp[-\xi\omega_n + j(\omega_d - \omega)]t |_0^\infty \\ & + \frac{\Gamma_n \hat{U}_n(x)}{j2\omega_d [-\xi\omega_n + j(\omega_d + \omega)]} \exp[-\xi\omega_n + j(\omega_d + \omega)]t |_0^\infty \end{aligned}$$
(B-9)

$$\begin{aligned}
H_{rn}(x, \omega) = & \\
& \frac{-\Gamma_n \hat{U}_n(x)}{j2\omega_d[-\xi\omega_n + j(\omega_d - \omega)]} \exp[-\xi\omega_n + j(\omega_d - \omega)] t |_0^\infty \\
& + \frac{\Gamma_n \hat{U}_n(x)}{j2\omega_d[-\xi\omega_n + j(\omega_d + \omega)]} \exp[-\xi\omega_n + j(\omega_d + \omega)] t |_0^\infty
\end{aligned} \tag{B-10}$$

$$\begin{aligned}
H_{rn}(x, \omega) = & \\
& \frac{-\Gamma_n \hat{U}_n(x)}{j2\omega_d[-\xi\omega_n + j(\omega_d - \omega)]} \exp[-\xi\omega_n t] \exp[j(\omega_d - \omega)] t |_0^\infty \\
& + \frac{\Gamma_n \hat{U}_n(x)}{j2\omega_d[-\xi\omega_n + j(\omega_d + \omega)]} \exp[-\xi\omega_n t] \exp[j(\omega_d + \omega)] t |_0^\infty
\end{aligned} \tag{B-11}$$

$$H_{rn}(x, \omega) = \\
\frac{\Gamma_n \hat{U}_n(x)}{j2\omega_d[-\xi\omega_n + j(\omega_d - \omega)]} - \frac{\Gamma_n \hat{U}_n(x)}{j2\omega_d[-\xi\omega_n + j(\omega_d + \omega)]} \tag{B-12}$$

$$H_{rn}(x, \omega) = \\
\frac{\Gamma_n \hat{U}_n(x)}{2\omega_d[-j\xi\omega_n - (\omega_d - \omega)]} - \frac{\Gamma_n \hat{U}_n(x)}{2\omega_d[-j\xi\omega_n - (\omega_d + \omega)]} \tag{B-13}$$

$$H_{rn}(x, \omega) = \frac{\Gamma_n \hat{U}_n(x)}{2\omega_d [-(\omega_d - \omega) - j\xi\omega_n]} - \frac{\Gamma_n \hat{U}_n(x)}{2\omega_d [-(\omega_d + \omega) - j\xi\omega_n]} \quad (B-14)$$

$$H_{rn}(x, \omega) = \frac{-\Gamma_n \hat{U}_n(x)}{2\omega_d [(\omega_d - \omega)j\xi\omega_n]} + \frac{\Gamma_n \hat{U}_n(x)}{2\omega_d [(\omega_d + \omega)j\xi\omega_n]} \quad (B-15)$$

$$H_{rn}(x, \omega) = \frac{\Gamma_n \hat{U}_n(x)}{2\omega_d [(\omega_d + \omega)j\xi\omega_n]} + \frac{-\Gamma_n \hat{U}_n(x)}{2\omega_d [(\omega_d - \omega)j\xi\omega_n]} \quad (B-16)$$

$$H_{rn}(x, \omega) = \left\{ \frac{\Gamma_n \hat{U}_n(x)}{2\omega_d} \right\} \left\{ \frac{1}{(\omega_d + \omega)j\xi\omega_n} + \frac{-1}{(\omega_d - \omega)j\xi\omega_n} \right\} \quad (B-17)$$

Recall

$$\frac{-\Gamma_n \hat{U}_n(x)}{(\omega_n^2 - \omega^2) + j(2\xi\omega\omega_n)} = \left\{ \frac{\Gamma_n \hat{U}_n(x)}{2\omega_d} \right\} \left\{ \frac{1}{\omega + \omega_d + j\xi\omega_n} + \frac{-1}{\omega - \omega_d + j\xi\omega_n} \right\} \quad (B-18)$$

Thus, the impulse response function is verified.