

RESPONSE OF A SINGLE-DEGREE-OF-FREEDOM SYSTEM SUBJECTED TO A UNIT STEP DISPLACEMENT

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Introduction

Consider the single-degree-of-freedom system in Figure 1.

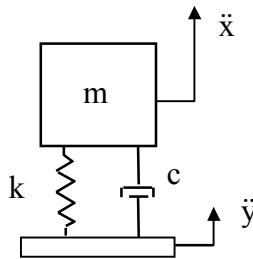


Figure 1.

where

- m is the mass
- c is the viscous damping coefficient
- k is the stiffness
- x is the absolute displacement of the mass
- y is the base input displacement

A free-body diagram is shown in Figure 2.

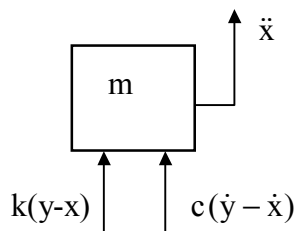


Figure 2.

Summation of forces in the vertical direction

$$\sum F = m\ddot{x} \quad (1)$$

$$m\ddot{x} = c(\dot{y} - \dot{x}) + k(y - x) \quad (2)$$

$$m\ddot{x} + c\dot{x} + kx = c\dot{y} + ky \quad (3)$$

$$\ddot{x} + (c/m)\dot{x} + (k/m)x = (c/m)\dot{y} + (k/m)y \quad (4)$$

$$(c/m) = 2\xi\omega_n \quad (5)$$

$$(k/m) = \omega_n^2 \quad (6)$$

where ω_n is the natural frequency in (radians/sec), and ξ is the damping ratio.

$$\ddot{x} + 2\xi\omega_n\dot{x} + \omega_n^2x = 2\xi\omega_n\dot{y} + \omega_n^2y \quad (7)$$

The base input displacement y is the unit step function $u(t)$. The base input velocity is the Dirac delta function $\delta(t)$.

Multiply the base input displacement by a scale factor D for a more general solution, even though the goal is to solve for a unit impulse.

$$\ddot{x} + 2\xi\omega_n\dot{x} + \omega_n^2x = 2\xi\omega_nD\delta(t) + \omega_n^2Du(t) \quad (8)$$

Now take the Laplace transform.

$$L\left\{\ddot{x} + 2\xi\omega_n\dot{x} + \omega_n^2x\right\} = L\left\{2\xi\omega_nD\delta(t) + \omega_n^2Du(t)\right\} \quad (9)$$

$$\begin{aligned} s^2X(s) - sx(0) - \dot{x}(0) \\ + 2\xi\omega_n sX(s) - 2\xi\omega_n x(0) \\ + \omega_n^2X(s) = 2\xi\omega_n D + \frac{\omega_n^2}{s} D \end{aligned} \quad (10)$$

$$\left\{s^2 + 2\xi\omega_n s + \omega_n^2\right\}X(s) + \{-1\}\dot{x}(0) + \{-s - 2\xi\omega_n\}x(0) = 2\xi\omega_n D + \frac{\omega_n^2}{s}D \quad (11)$$

$$\left\{s^2 + 2\xi\omega_n s + \omega_n^2\right\}X(s) = \dot{x}(0) + \{s + 2\xi\omega_n\}x(0) + 2\xi\omega_n D + \frac{\omega_n^2}{s}D \quad (12)$$

$$\left\{s^2 + 2\xi\omega_n s + \omega_n^2\right\}X(s) = s x(0) + \dot{x}(0) + 2\xi\omega_n [x(0) + D] + \frac{\omega_n^2}{s}D \quad (13)$$

$$X(s) = \frac{s x(0)}{\left\{s^2 + 2\xi\omega_n s + \omega_n^2\right\}} + \frac{\dot{x}(0) + 2\xi\omega_n [x(0) + D]}{\left\{s^2 + 2\xi\omega_n s + \omega_n^2\right\}} + \frac{\omega_n^2 D}{s \left\{s^2 + 2\xi\omega_n s + \omega_n^2\right\}} \quad (14)$$

Consider the denominator term,

$$s^2 + 2\xi\omega_n s + \omega_n^2 = (s + \xi\omega_n)^2 + \omega_n^2 - (\xi\omega_n)^2 \quad (15)$$

$$s^2 + 2\xi\omega_n s + \omega_n^2 = (s + \xi\omega_n)^2 + \omega_n^2(1 - \xi^2) \quad (16)$$

Now define the damped natural frequency,

$$\omega_d = \omega_n \sqrt{1 - \xi^2} \quad (17)$$

Substitute equation (17) into (16),

$$s^2 + 2\xi\omega_n s + \omega_n^2 = (s + \xi\omega_n)^2 + \omega_d^2 \quad (18)$$

Substitute equation (18) into (14).

$$X(s) = \frac{s x(0)}{(s + \xi \omega_n)^2 + \omega_d^2} + \frac{\dot{x}(0) + 2\xi \omega_n [x(0) + D]}{(s + \xi \omega_n)^2 + \omega_d^2} + \frac{\omega_n^2 D}{s \{(s + \xi \omega_n)^2 + \omega_d^2\}} \quad (19)$$

$$X(s) = \frac{(s + \xi \omega_n) x(0)}{(s + \xi \omega_n)^2 + \omega_d^2} + \frac{\dot{x}(0) + \xi \omega_n x(0) + 2\xi \omega_n D}{(s + \xi \omega_n)^2 + \omega_d^2} + \frac{\omega_n^2 D}{s \{(s + \xi \omega_n)^2 + \omega_d^2\}} \quad (20)$$

Perform partial fraction expansion per Appendix A.

$$\frac{1}{s \{(s + \xi \omega_n)^2 + \omega_d^2\}} = \left(\frac{1}{\omega_n^2} \right) \frac{1}{s} + \left(\frac{-1}{\omega_n^2} \right) \frac{(s + 2\xi \omega_n)}{(s + \xi \omega_n)^2 + \omega_d^2} \quad (21)$$

$$\begin{aligned} X(s) &= \frac{(s + \xi \omega_n) x(0)}{(s + \xi \omega_n)^2 + \omega_d^2} + \frac{\dot{x}(0) + \xi \omega_n x(0) + 2\xi \omega_n D}{(s + \xi \omega_n)^2 + \omega_d^2} \\ &\quad + \left(\frac{\omega_n^2 D}{\omega_n^2} \right) \frac{1}{s} + \left(\frac{-\omega_n^2 D}{\omega_n^2} \right) \frac{(s + 2\xi \omega_n)}{(s + \xi \omega_n)^2 + \omega_d^2} \end{aligned} \quad (22)$$

$$\begin{aligned} X(s) &= \frac{(s + \xi \omega_n) x(0)}{(s + \xi \omega_n)^2 + \omega_d^2} + \frac{\dot{x}(0) + \xi \omega_n x(0)}{(s + \xi \omega_n)^2 + \omega_d^2} \\ &\quad + \frac{1}{s} D + \frac{-Ds}{(s + \xi \omega_n)^2 + \omega_d^2} \end{aligned} \quad (23)$$

Take the inverse Laplace transform using standard tables.

$$\begin{aligned}
 X(s) &= \frac{(s+\xi\omega_n)x(0)}{(s+\xi\omega_n)^2 + \omega_d^2} + \frac{\dot{x}(0) + \xi\omega_n x(0)}{(s+\xi\omega_n)^2 + \omega_d^2} \\
 &+ \frac{1}{s}D + \frac{-Ds}{(s+\xi\omega_n)^2 + \omega_d^2}
 \end{aligned} \tag{24}$$

$$\begin{aligned}
 x(t) &= \\
 &+ \exp(-\xi\omega_n t) \left\{ [\xi\omega_n x(0)] \cos(\omega_d t) + \left[\frac{\dot{x}(0) + \xi\omega_n x(0)}{\omega_d} \right] \sin(\omega_d t) \right\} \\
 &+ D u(t) \\
 &- D \exp(-\xi\omega_n t) \left\{ \cos(\omega_d t) + \left[\frac{-\xi\omega_n}{\omega_d} \right] \sin(\omega_d t) \right\}
 \end{aligned} \tag{25}$$

$$\begin{aligned}
 x(t) &= \\
 &+ \exp(-\xi\omega_n t) \left\{ [\xi\omega_n x(0)] \cos(\omega_d t) + \left[\frac{\dot{x}(0) + \xi\omega_n x(0)}{\omega_d} \right] \sin(\omega_d t) \right\} \\
 &+ D \left\{ u(t) - \exp(-\xi\omega_n t) \left\{ \cos(\omega_d t) + \left[\frac{-\xi\omega_n}{\omega_d} \right] \sin(\omega_d t) \right\} \right\}
 \end{aligned} \tag{26}$$

Example

Consider a single-degree-of-freedom system with a natural frequency of 100 Hz and 5% damping. The system has zero initial velocity and zero initial displacement. The system is subjected to a unit displacement at $t = 0^+$, which is multiplied by a coefficient of $D = 1$ mm. The response is shown in Figure 3.

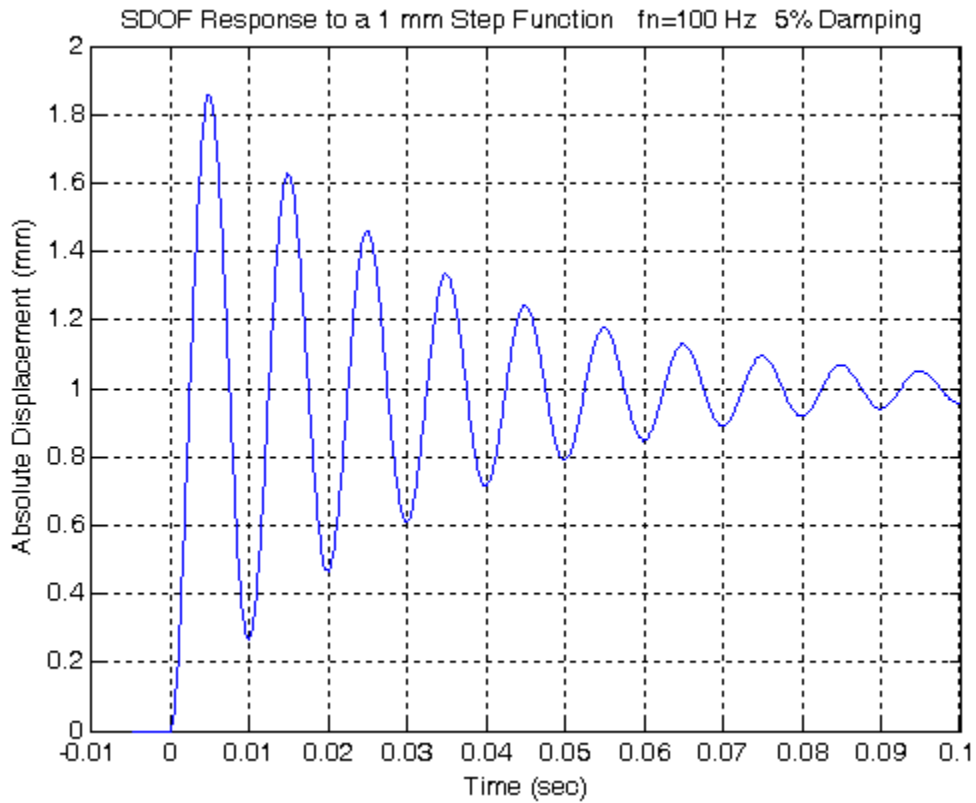


Figure 3.

APPENDIX A

Partial Fraction Expansion

$$\frac{1}{s\{(s + \xi\omega_n)^2 + \omega_d^2\}} = \frac{A}{s} + \frac{Bs + C}{(s + \xi\omega_n)^2 + \omega_d^2} \quad (\text{A-1})$$

$$\frac{A}{s}\{(s + \xi\omega_n)^2 + \omega_d^2\} + \frac{Bs + C}{(s + \xi\omega_n)^2 + \omega_d^2}s\{(s + \xi\omega_n)^2 + \omega_d^2\} = 1 \quad (\text{A-2})$$

$$A\{(s + \xi\omega_n)^2 + \omega_d^2\} + Bs^2 + Cs = 1 \quad (\text{A-3})$$

$$s^2 + 2\xi\omega_n s + \omega_n^2 = (s + \xi\omega_n)^2 + \omega_d^2 \quad (\text{A-4})$$

$$A\{s^2 + 2\xi\omega_n s + \omega_n^2\} + Bs^2 + Cs = 1 \quad (\text{A-5})$$

$$\{A + B\}s^2 + \{2\xi\omega_n A + C\}s + A\omega_n^2 = 1 \quad (\text{A-6})$$

$$\{A + B\}s^2 = 0 \quad (\text{A-7})$$

$$\{2\xi\omega_n A + C\}s = 0 \quad (\text{A-8})$$

$$A\omega_n^2 = 1 \quad (\text{A-9})$$

$$A = \frac{1}{\omega_n^2} \quad (\text{A-10})$$

$$B = \frac{-1}{\omega_n^2} \quad (\text{A-11})$$

$$C = -2\xi\omega_n A \quad (\text{A-12})$$

$$C = \frac{-2\xi}{\omega_n} \quad (\text{A-13})$$

$$\frac{1}{s\{(s + \xi\omega_n)^2 + \omega_d^2\}} = \left(\frac{1}{\omega_n^2}\right)\frac{1}{s} + \frac{\left(\frac{-1}{\omega_n^2}\right)s + \left(\frac{-2\xi}{\omega_n}\right)}{(s + \xi\omega_n)^2 + \omega_d^2} \quad (\text{A-14})$$

$$\frac{1}{s\{(s + \xi\omega_n)^2 + \omega_d^2\}} = \left(\frac{1}{\omega_n^2}\right)\frac{1}{s} + \left(\frac{-1}{\omega_n^2}\right)\frac{(s + 2\xi\omega_n)}{(s + \xi\omega_n)^2 + \omega_d^2} \quad (\text{A-15})$$

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